

User: Perspective
1387 Collection | Body07.0037
Rectifying Bone
Objects: 11,918
Vertices: 92,149,801
Edges: 62,361,921
Faces: 22,286,198
Triangles: 44,286,198



ADE-1 Industrial System Software

From model to fully operational
production systems

**We don't optimize factories.
We generate them.**



ADE-1 Autonomous Decision Engineering



Developed by Tocotech Group
+20 years of industrial innovation



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Introduction

Today I will introduce a new approach to industrial process optimization.
After 22 years, **we are bringing a VISION to LIFE**

ADE-1 is not a classical planning or scheduling tool.
It is a system engine that models, simulates, and runs industrial production
using the same underlying structure.

It is **NOT** just a “simulation system”, it is an
Autonomous Decision Engineering, a “**living organism playing chess for a
better order sequence**”

**We generate systems where correct decisions emerge automatically from
the model.**



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Introduction

From a single model, the system automatically generates:

- **production control**
- **machine control**
- **databases**
- **Visualization**

Using a 360° context, real-time feedback, and user-defined priority weights, to brute-force the optimal production sequence

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The Problem

Industrial systems are controlled by multiple disconnected layers: ERP, MES, PLC, planning tools. They are losing efficiency every day — not because of lack of data, but because of fragmented decision systems.

Companies rely on **disconnected tools** (ERP, MES, planning, control), each operating on a partial view of reality.

These systems cannot represent the real physical process

This leads to:

- **Suboptimal production decisions**
- **High operational variability**
- **Hidden inefficiencies that scale with complexity**
- **In complex environments, human-driven planning simply does not scale**



This leads to inefficiencies that are widely accepted as unavoidable.



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Why Existing Solutions Fail

No system today provides a unified, executable model of the full production system

Current industrial software does **not model reality** — it approximates it. Each system layer amplifies the problem:

- Planning tools ignore execution constraints
- Execution systems lack global optimization
- Control systems operate locally

As a result:

- Decisions are made on incomplete models
- Optimization is local, not global
- Systems become unstable under disruption



The core issue:

Existing systems optimize decisions. They do not model the system itself.

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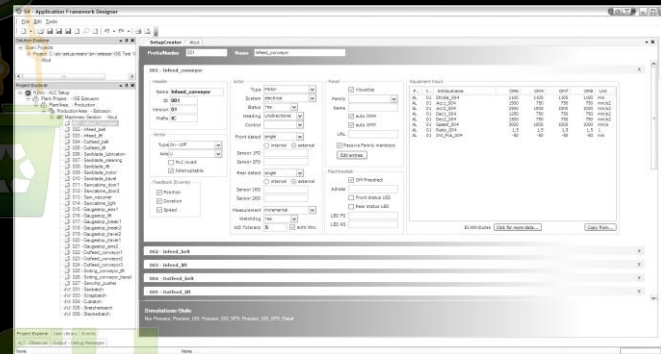
The Core Idea

We take a fundamentally different approach.

Current systems require manual programming, integration, and maintenance.

**ADE-1 require NO coding. The model is not a representation.
It becomes the executable system itself.**

- **Materials are tracked as real identities**
- **Machines define physical constraints**
- **Processes are ruled-based transformations**



This creates a system where:

Correct decisions are not calculated → they emerge from the model

The model is not a simplification

It behaves like the real system

It is a functional representation of the process itself



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How ADE-1 Works

The same model generates both simulation and real system execution. No abstraction layers between model and execution.

Material is never abstracted away. Instead, it is tracked continuously through transformations.

Objects are tracked spatially in real-time with millimetric precision

At machine boundaries:

- **Objects are consumed**
- **New objects are created**
- **Identity and genealogy are preserved**



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How It Works

For example:

A cooling batch is incrementally transformed into a saw batch, which is then transformed into stacker batches and by-products.

During this process, source and target objects coexist until the transformation is complete.



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This guarantees full consistency and traceability at all times.



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Scenario Engine

Unlike traditional APS, this system evaluates physically valid scenarios only.

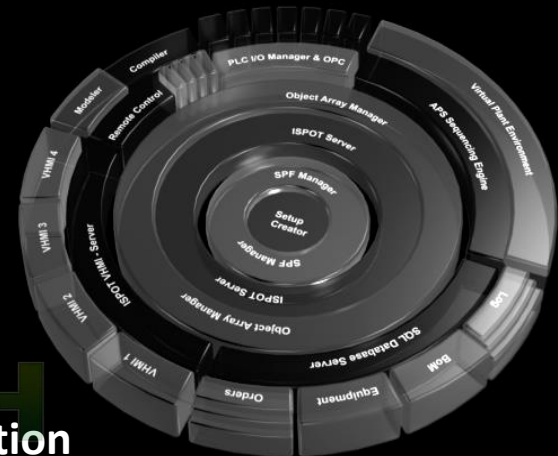
On top of this model, we run a scenario-based planning engine. The system generates and evaluates a large number of possible production scenarios.

These scenarios vary parameters such as:

- order sequence
- lot sizes
- batch composition
- machine configurations
- Enables real-time “rolling production” optimization

Each scenario is simulated over a defined time horizon.

**The outcome is not estimated —
It is computed through the model.**



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Key Differentiator

- ✓ No heuristics
- ✓ No approximations
- ✓ No manual rule tuning
- ✓ No predefined rules

It evaluates thousands of physically valid production scenarios and selects the best outcome.

No need for PLC programming — system generates control logic automatically

This leads to:

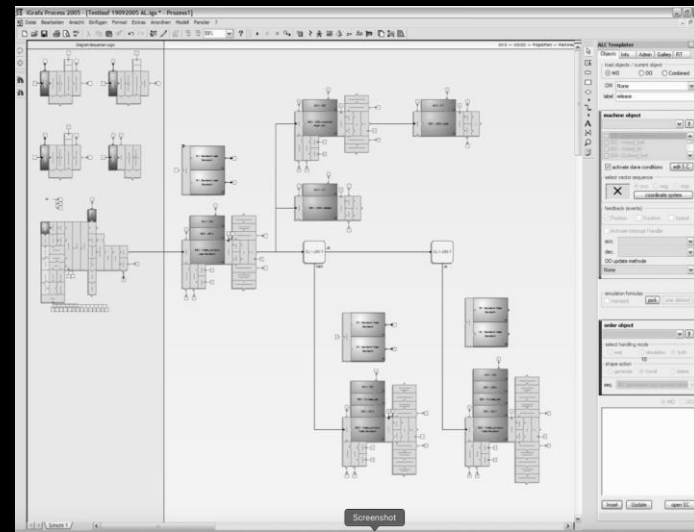
Higher accuracy

More stable operations

Results that outperform human planning

The intelligence is not coded

It emerges from the structure of the system



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Why It Works

All scenarios are physically valid by design. Object-matrix architecture replaces traditional database bottlenecks → 1000x performance improvement

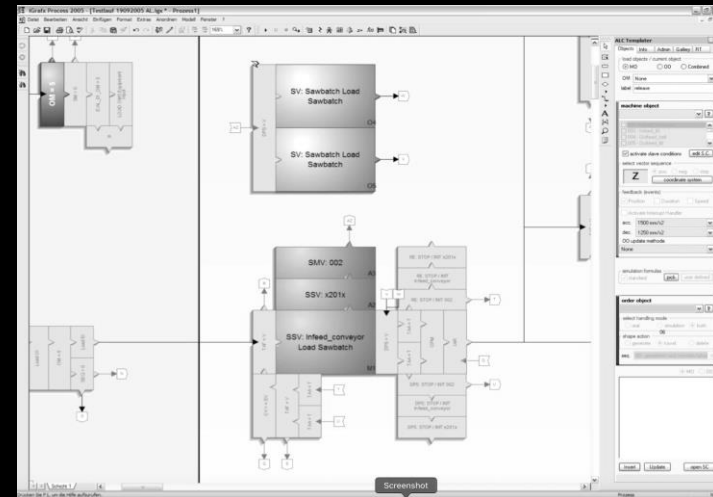
The effectiveness of the approach is based on constraint integrity.

The system enforces:

- conservation of material
- geometric feasibility
- machine capabilities
- process timing

This ensures that all simulated scenarios are physically valid.

As a result, the search space is significantly reduced, and brute-force evaluation becomes feasible.



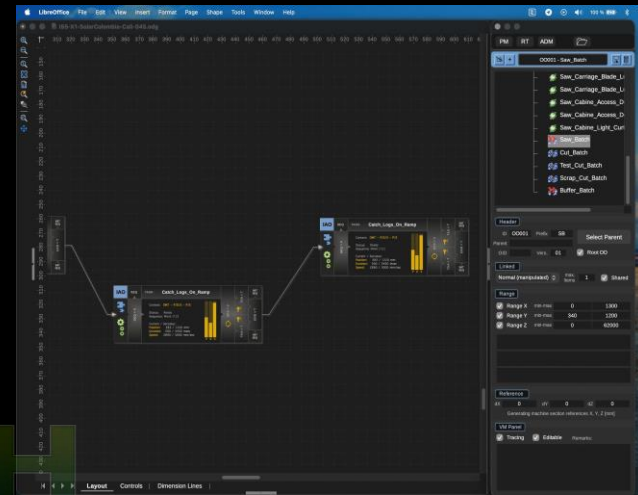
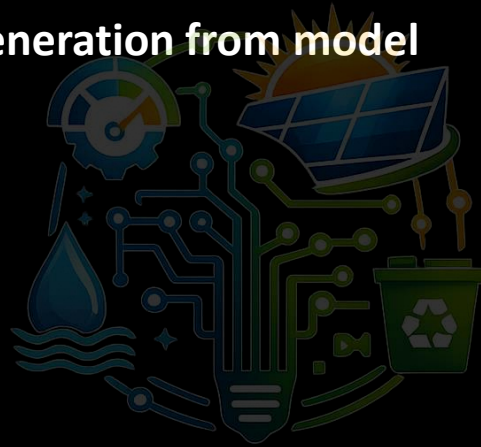
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Why ADE-1 is Unique

This framework unifies multiple traditionally separate domains:

- Automatic system generation from model
- Process modeling
- Production planning
- Execution logic
- Control System
- Machine logic
- Database
- Visualization
- Documentation



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All operate on a single, consistent representation.



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Why ADE-1 is different

In addition:

- Every material transformation is tracked
- Full genealogy is preserved
- Dynamic batch formation is supported

Traditional Systems

- fragmented
- manual integration
- coding required
- approximation

ADE-1

- unified
- automatic generation
- no code
- real system

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This level of integration is not available in conventional systems.



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This is not a concept.
This is a running system.

The interface is divided into several sections:

- OBSERVER:** A 3D simulation of a robotic arm in a factory environment.
- OBJECT VIEWER:** A pop-up window showing details for the selected object: "zufuehrlgang2-steher".
- I.SPOT VM PANEL:** A list of process IDs (P20-0001 to P20-0009) with control buttons (NEW, EDIT, DEL, UNDO, GANG, START).
- PREVIOUS ORDER:** A table showing order details for the previous cycle.
- CURRENT ORDER:** A table showing order details for the current cycle.
- NEXT ORDER:** A table showing order details for the next cycle.
- COMMUNICATION:** A panel with navigation buttons (PICK, HOME) and a volume control slider.
- ALARMS:** A panel with buttons for "SHOW DETAILS", "OBJECT VIEWER", and "ACK_ALARM", and a message display area.

OBJECT VIEWER

OBJECT	zufuehrlgang2-steher
ID	
ORDER	
FUNCTION	localhost

I.SPOT VM PANEL

P20-0001	NEW
P20-0002	EDIT
P20-0003	DEL
P20-0004	
P20-0005	UNDO
P20-0006	GANG
P20-0009	START

PREVIOUS ORDER

	SET	CUR
section/order	80	0
section/sawbatch	9	0
cut-/sawbatch	11	0
sample		
	sim	curr
cycle time		

CURRENT ORDER

	SET	CUR
section/order	800	0
section/sawbatch	14	0
cut-/sawbatch	24	0
sample		
	sim	curr
cycle time		

NEXT ORDER

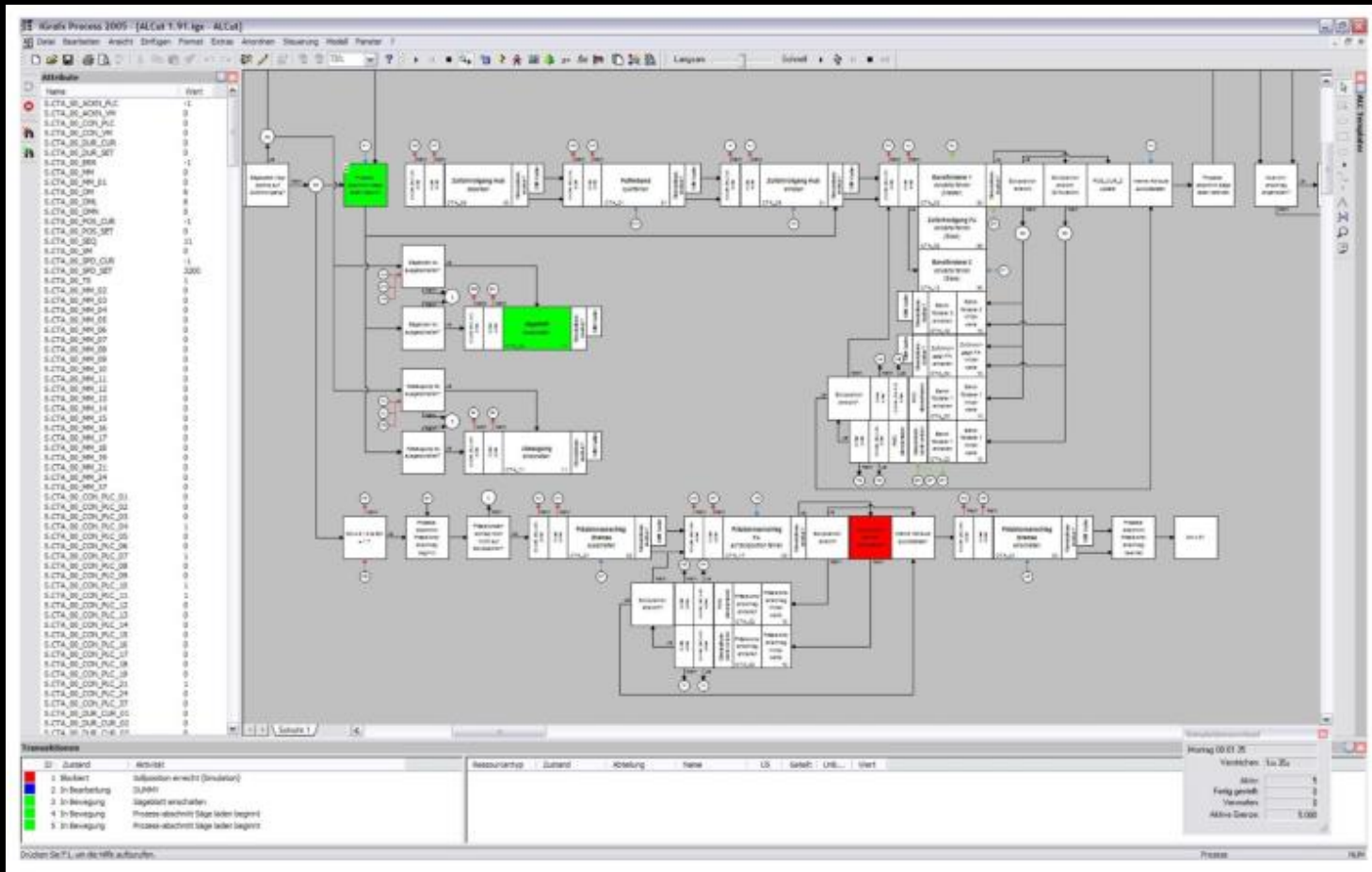
	SET	CUR
section/order	14	0
section/sawbatch	14	0
cut-/sawbatch	8	0
sample		
	sim	curr
cycle time		



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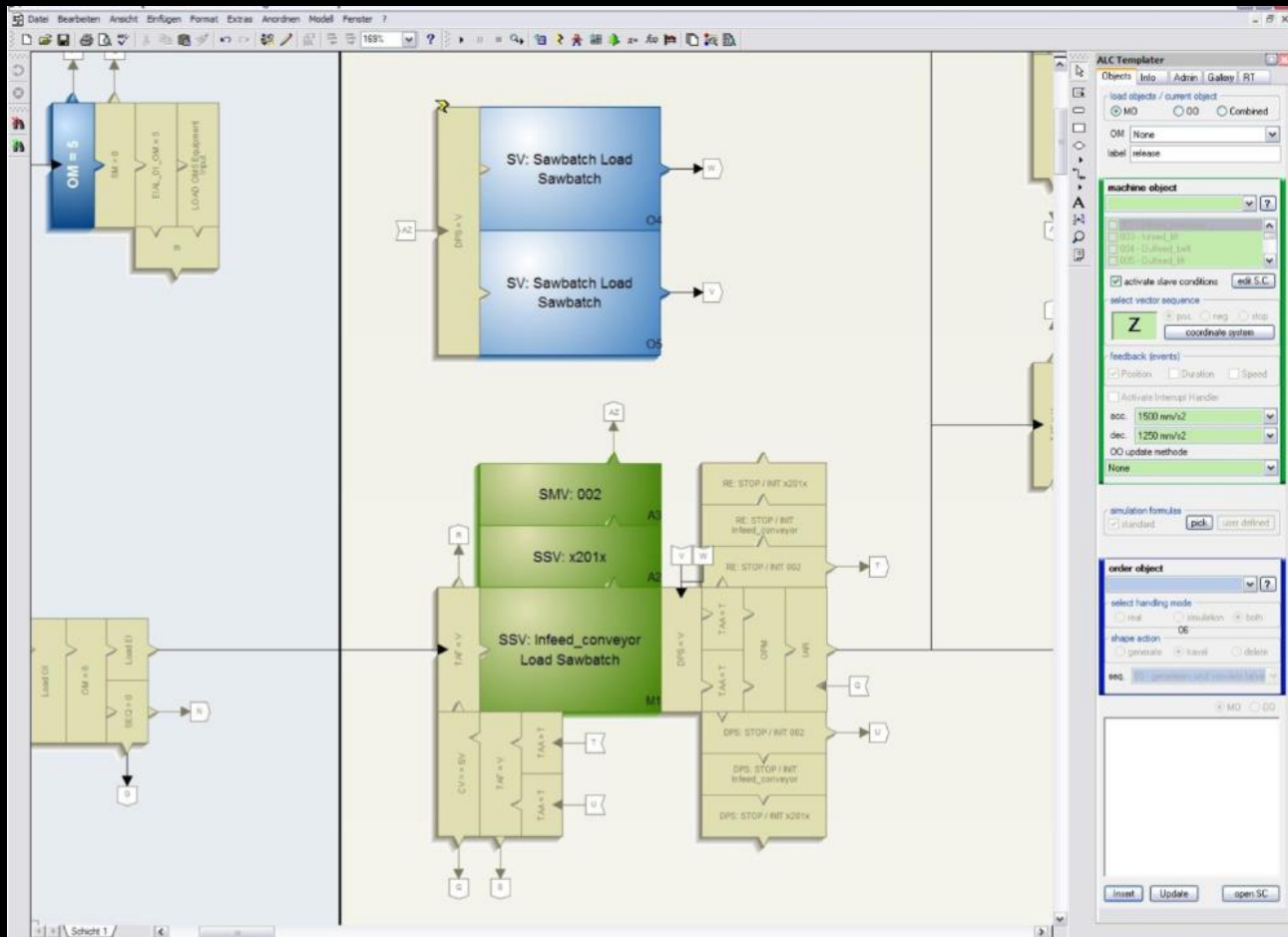
This is not a concept.
This is a running system.



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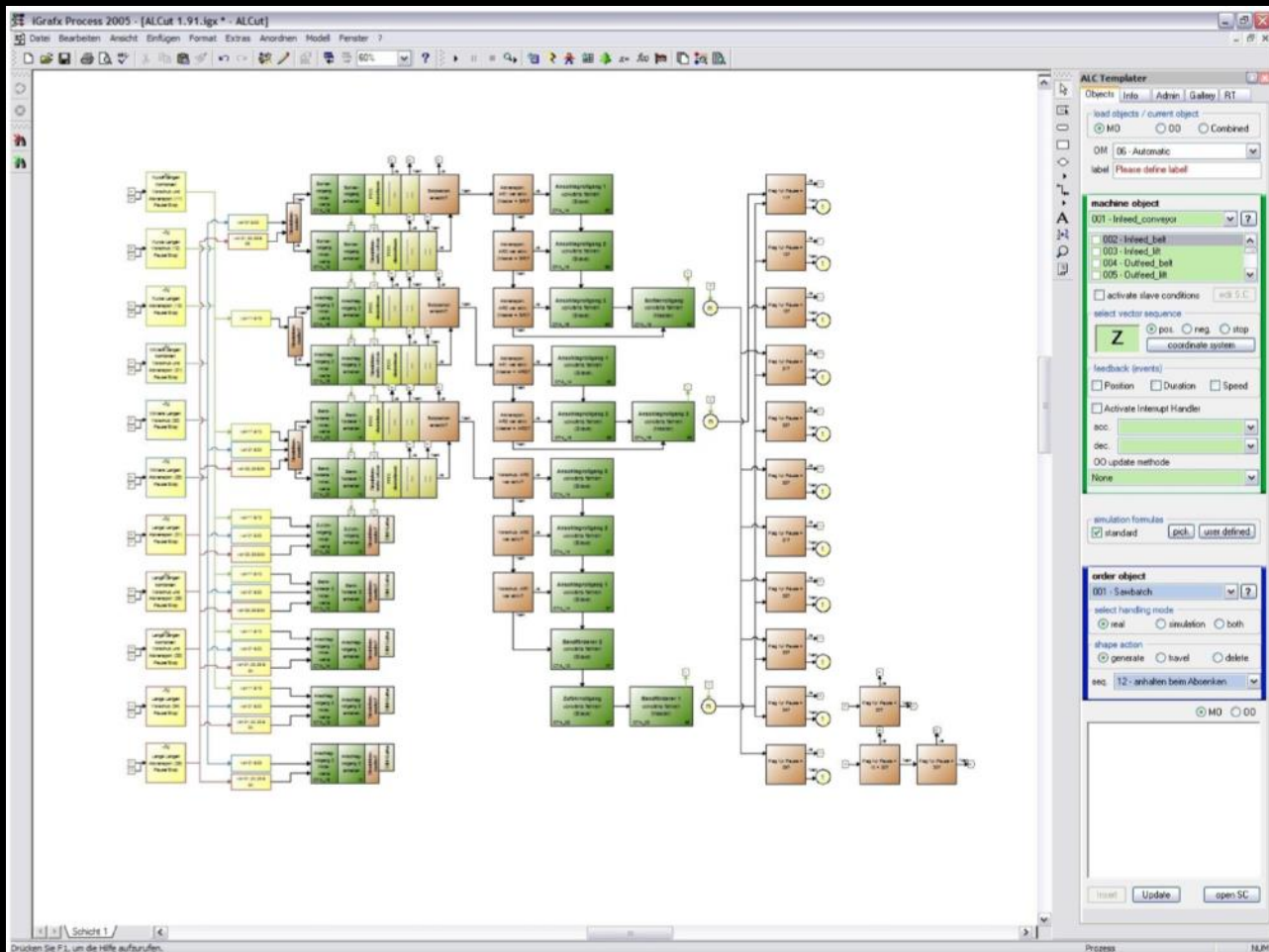
This is not a concept.
This is a running system.



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This is not a concept.
This is a running system.



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Performance & Scalability

The system is designed for high computational throughput. Performance advantages:

- up to 1000x faster than database-based systems
- millions of operations per second
- sub-millisecond response time
- scalable across hardware
- scenarios can be evaluated in parallel
- runtime instances can scale horizontally
- performance increases directly with available hardware
- Future architectures, including FPGA-based acceleration, can further increase performance.



This opens the possibility for near real-time global optimization.



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Business Impact

Measured impact (validated environments):

- 20–40% efficiency improvement
- 10–25% throughput increase
- Significant reduction in material waste
- Improved energy efficiency

Most importantly:

Ability to handle complexity beyond human capability.



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Use Cases

While initially developed for metal processing, the underlying model is general.

It applies to any domain involving:

- **material flow**
- **transformation processes**
- **constrained systems**

Examples include:

- **Bulk materials**
- **Fluids and gases**
- **Logistics networks**
- **Energy distribution**
- **Recycling systems**
- **Including hybrid systems (solids + fluids)**



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Vision

Our long-term vision is to establish a **universal execution layer for industrial systems**

A system capable of describing:

- **material**
- **energy**
- **and process interactions in a unified, executable form.**

Effectively, a discrete physics layer for industrial systems.



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Competitive Position

ADE-1 replaces multiple systems instead of improving one

Existing solutions rely on:

- heuristics
- approximations
- domain-specific optimizations

Our approach is fundamentally different:

- it is model-driven
- physically consistent
- and scenario-based



This creates a structural advantage rather than an incremental improvement.



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Closing

To summarize:

- From model to fully running system — automatically
- We are not teaching machines how to decide.
- We are building systems in which the correct decision is the natural outcome of the model.



This represents a shift from decision optimization to system-level intelligence.



THANKS FOR YOUR CHOICE!



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