

# SIG788

Engineering AI solutions

Distinction Task 5

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Target = Distinction

## Object Detection using Azure's Custom Vision API

### Introduction

Project uses Microsoft Azure's Custom Vision API to detect and categorize objects in vehicle tracking in a video.

### Objective:

The goal is to create a program that can accurately identify objects the objects in video for vehicle tracking using Azure's Custom Vision SDK. The program will highlight detected objects, demonstrating its practical application in real-world scenarios like vehicle tracking analysis.

### Approach:

The project involves below steps:

- **Video Selection:** Choose three diverse vehicle videos under different conditions.
- **Image Extraction:** Extract images at one-second intervals from these videos, capturing vehicles from various angles and distances.
- **Azure Project Setup:** Create an Azure Custom Vision project with object detection and multi-label prediction capabilities.
- **Image Tagging:** Accurately tag 120 images with bounding boxes around each vehicle using the parquet bounding box information for the selected video.
- **Model Training:** Train the model using tagged images.
- **Model Evaluation:** Evaluate the model's performance using precision, recall, and mAP metrics.
- **Model Deployment:** Deploy the trained model efficiently, considering the expected frequency and volume of video processing.
- **Model Validation:** Test the model's generalization capabilities and real-world applicability with new videos not included in the training set.

### Azure Custom Vision:

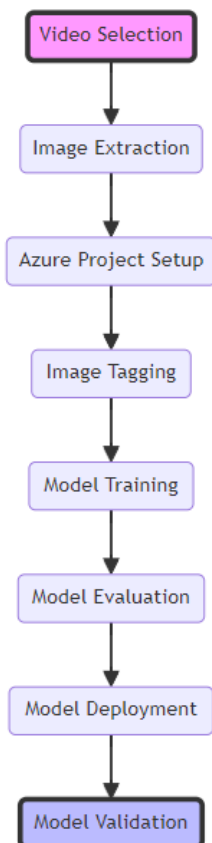
Azure **Custom Vision** is a part of Azure AI Services which allows to build, deploy, and improve own image classifiers.

### Key features include:

- **Customization to user Scenario:** can set model to perceive a particular object for a use case.
- **Intuitive Model Creation:** Easily build image identifier model using the simple interface.

- **Flexible Deployment:** Run AI Custom Vision in the cloud or on the edge in containers.
- **Built-in Security:** Rely on enterprise-grade security and privacy for data and any trained models.
- **Achieve Accuracy Without Complexity:** Start training computer vision model by simply uploading and labelling a few images.
- **Accelerate Model Creation:** A user-friendly interface walks through developing and deploying custom computer vision models.
- **Deploy Anywhere:** From the Cloud to the Edge: Run models wherever we need them and according to unique scenario and requirements.

Flowchart:

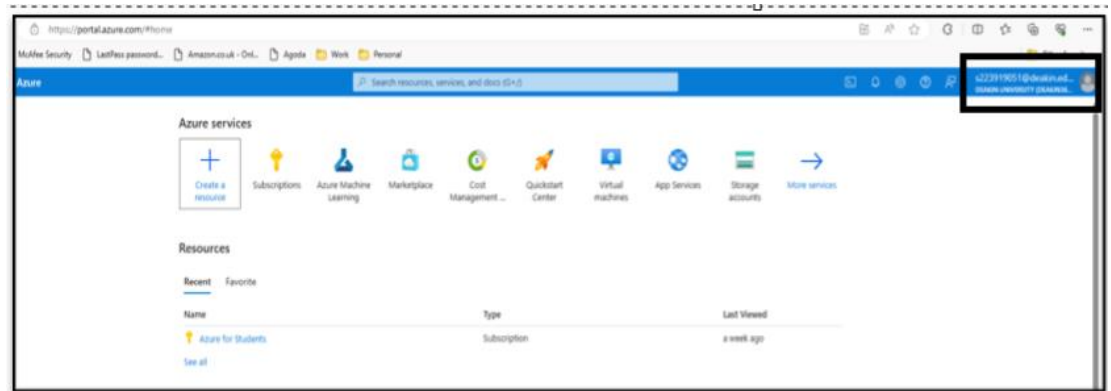


Creating Azure Custom Vision:

- **Sign in to Azure Portal:** Azure Portal and sign in with Microsoft account Deakin credentials.

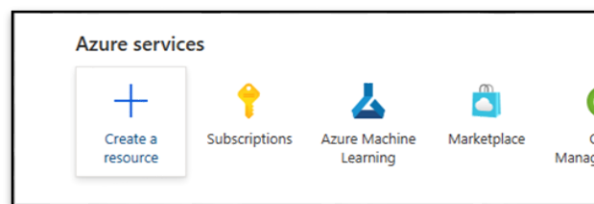
Link: <https://portal.azure.com/>

**Landing Page:**

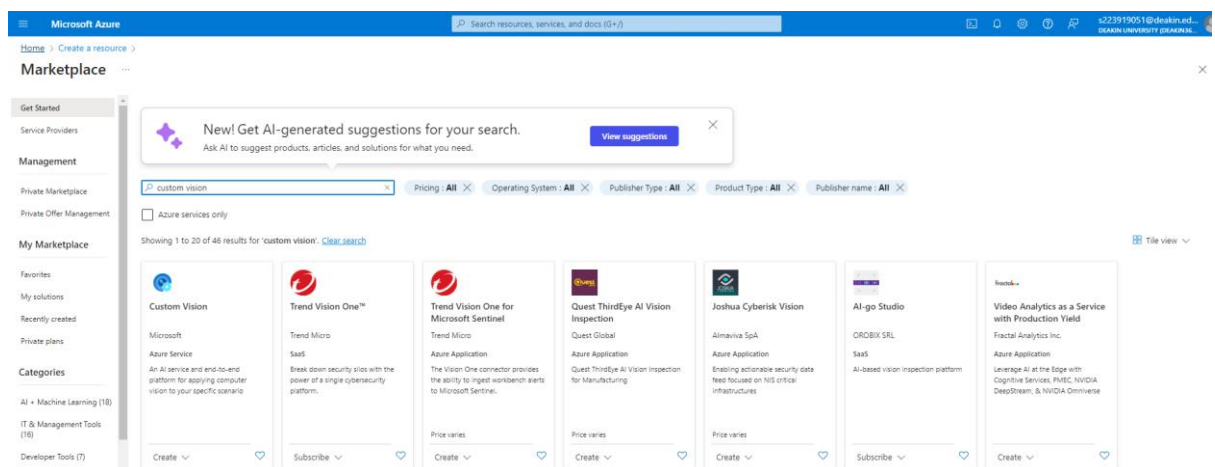


➤ **Create a New Workspace:**

- Click on **Create a resource** at the top-left corner.



- Search for **Custom Vision** & select **Create** from **Custom Vision** to initiate the creation process.



➤ **Configure the Workspace:**

- Create option: Select **Both (Prediction + Training)**
- Creating a resource group **RG-S223919051-Task5**
- Instance Detail name **ID-S223919051-Task**
- Choose an Azure region **Central India** which is close to my location.
- Pricing tier has been selected with Free Tier
  - Training **"Free F0 (2 Transaction per second, 2 projects)"**
  - Prediction **"Free F0 (2 Transaction per second)"**
- Then click review and create

Basics

Network

Tags

Review + create

Customize and embed state-of-the-art computer vision for specific domains. Build frictionless customer experiences, optimize manufacturing processes, accelerate digital marketing campaigns -- and more. No machine learning expertise is required.

[Learn more](#)

Create options \*

☒ Both  
☐ Prediction  
☐ Training

**Project Details**

Subscription \* ⓘ 

Azure for Students

Resource group \* ⓘ 

(New) RG-S223919051-Task5

  
[Create new](#)

**Instance Details**

A training resource and a prediction resource will be created in same region.

Region ⓘ 

Central India

Name \* ⓘ 

ID-S223919051-Task5

**Training Resource**

Select pricing for training Resource.

Training pricing tier \* ⓘ 

Free F0 (2 Transactions per second, 2 Projects)

  
[View full pricing details](#)

**Prediction Resource**

Select pricing for prediction Resource.

Prediction pricing tier \* ⓘ 

Free F0 (2 Transactions per second)

  
[View full pricing details](#)


Previous

Next

Review + create

- **Review and Create:** After configuring the details click on **Review + create** button. Once Azure validates configuration. Click on **Create** button to deploy workspace.


**Review:**

 Microsoft Azure Search

Home > Create a resource > Marketplace >

## Create Custom Vision ...

Basics Network Tags Review + create

 [View automation template](#)

### TERMS

By clicking "Create", I (a) agree to the legal terms and privacy statement(s) associated with the Marketplace offering(s) listed above; (b) authorize Microsoft to bill my current payment method for the fees associated with the offering(s), with the same billing frequency as my Azure subscription; and (c) agree that Microsoft may share my contact, usage and transactional information with the provider(s) of the offering(s) for support, billing and other transactional activities. Microsoft does not provide rights for third-party offerings. See the [Azure Marketplace Terms](#) for additional details.

### Basics

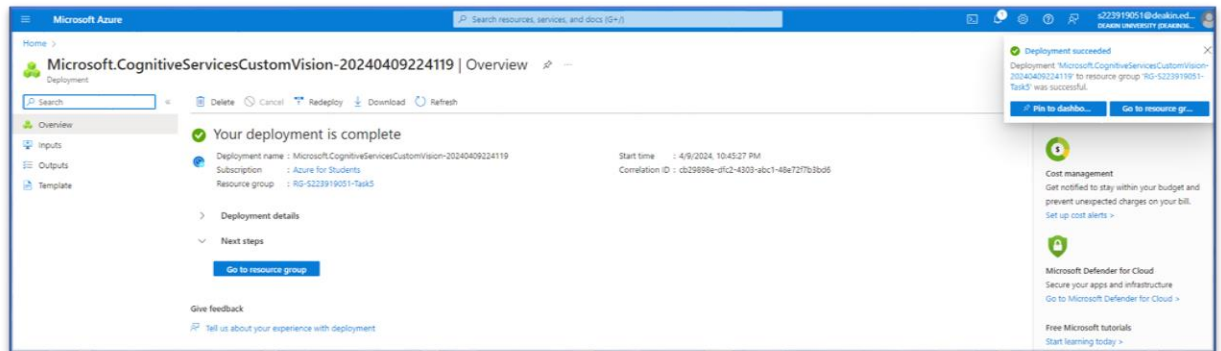
Create options	Both
Subscription	Azure for Students
Resource group	RG-S223919051-Task5
Region	Central India
Name	ID-S223919051-Task5
Training pricing tier	Free F0 (2 Transactions per second, 2 Projects)
Prediction pricing tier	Free F0 (2 Transactions per second)

### Network

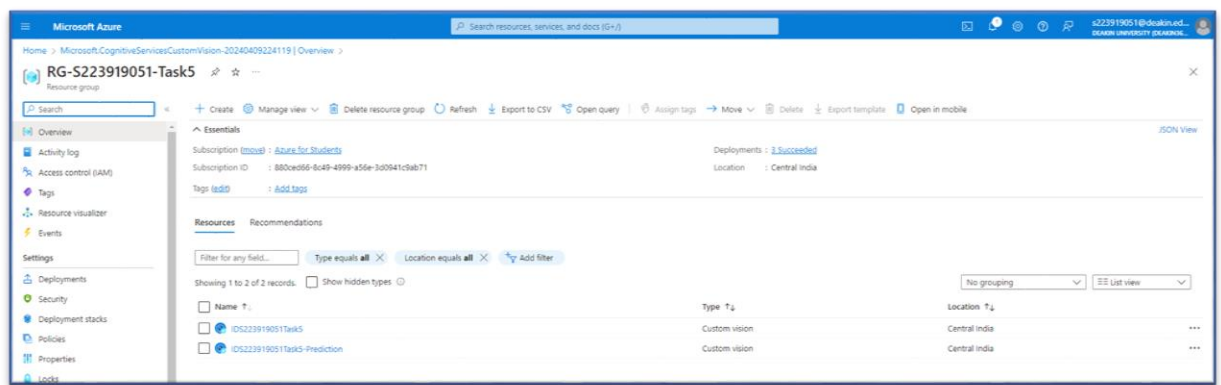
Type	All networks, including the internet, can access this resource.
------	---

Previous Next Create

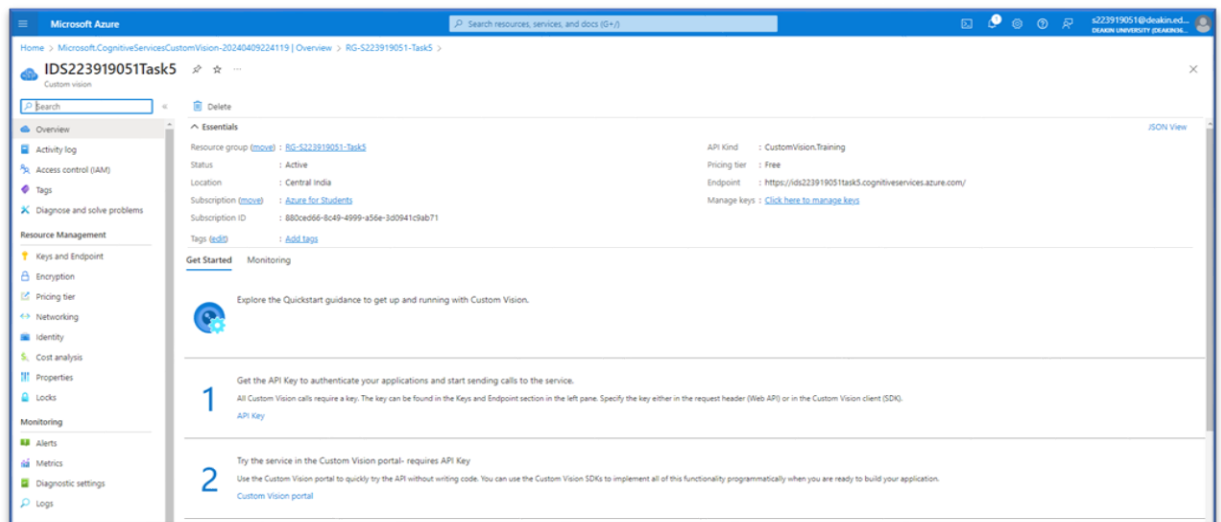
## Workspace deployed:



## Training and Prediction spaces are deployed

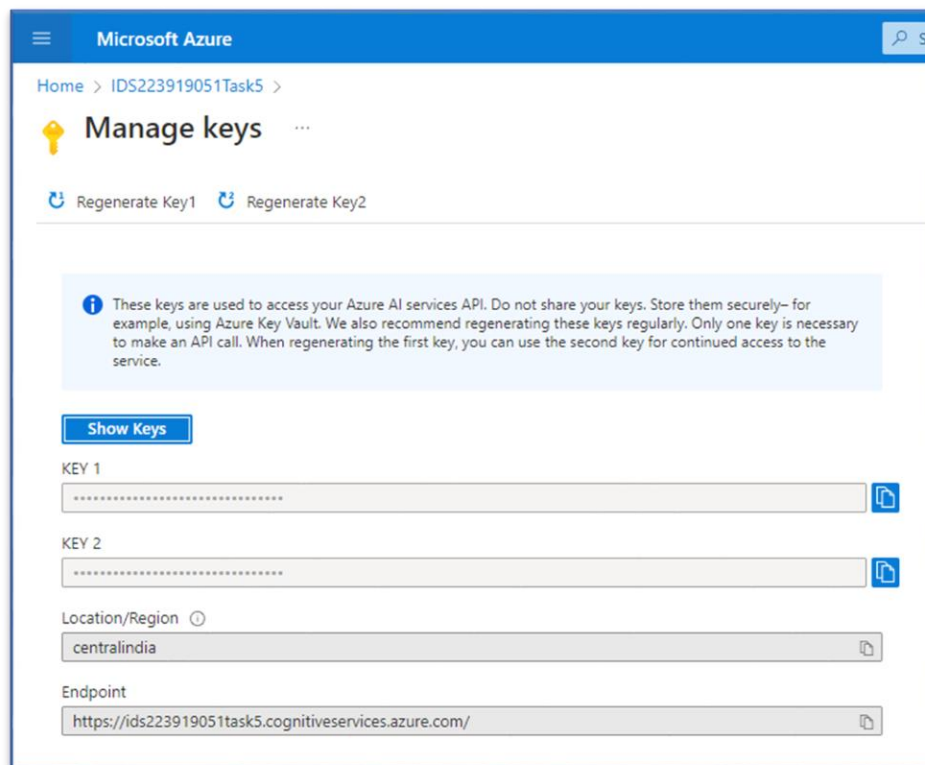


## Training Custom Vision:

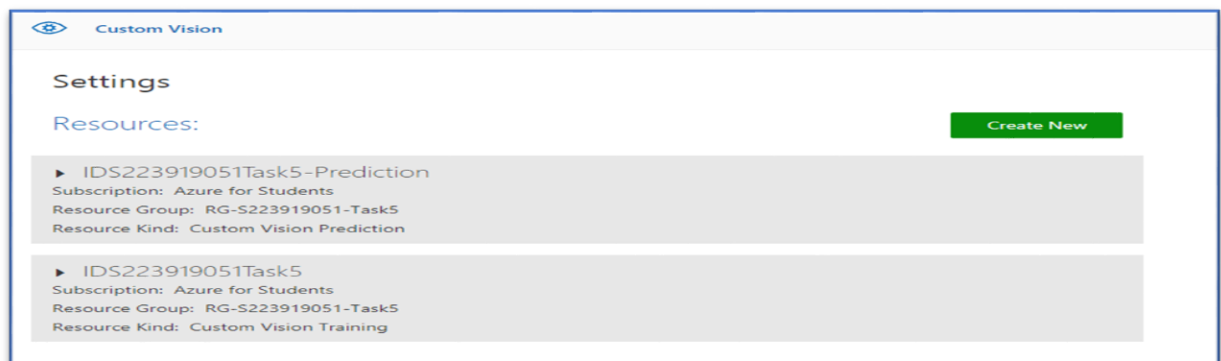
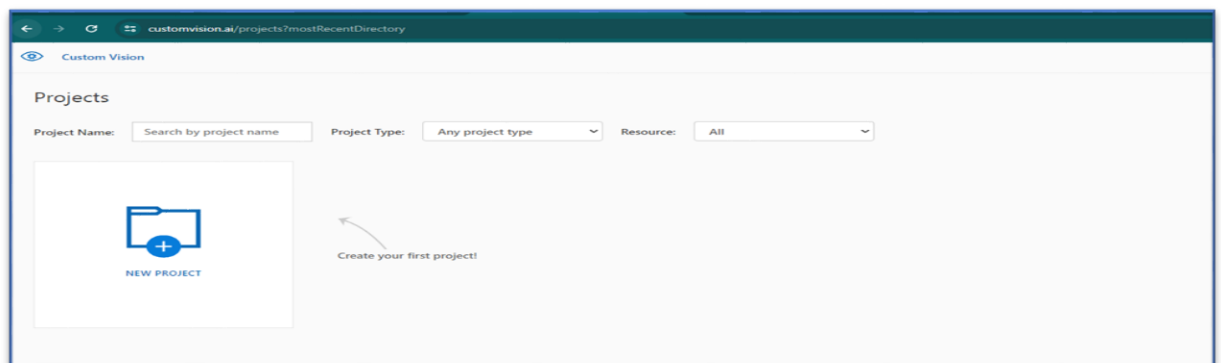




## 1. Get the API Key to authenticate



## 2. Custom Vision Portal





Now let's proceed to create the Python SDK;


### Pre-requisites:

Install pre-requisites for Computer Vision in Anaconda prompt.

- pip install azure-cognitiveservices-vision-customvision
- pip install pillow
- pip install python-dotenv




 **azure-cognitiveservices-vision-computervision:** This command installs the Azure Custom Vision library, which allows to interact with the Azure Custom Vision service from Python applications.

 **pillow:** A PIL fork, Pillow adds image processing capabilities to Python, including opening, manipulating, and saving various image file formats. It's commonly used for tasks like resizing, applying filters, and handling different image formats.

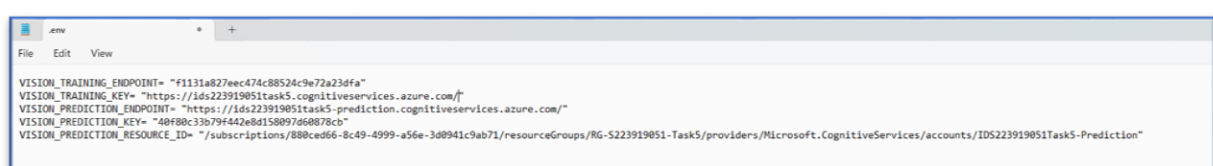
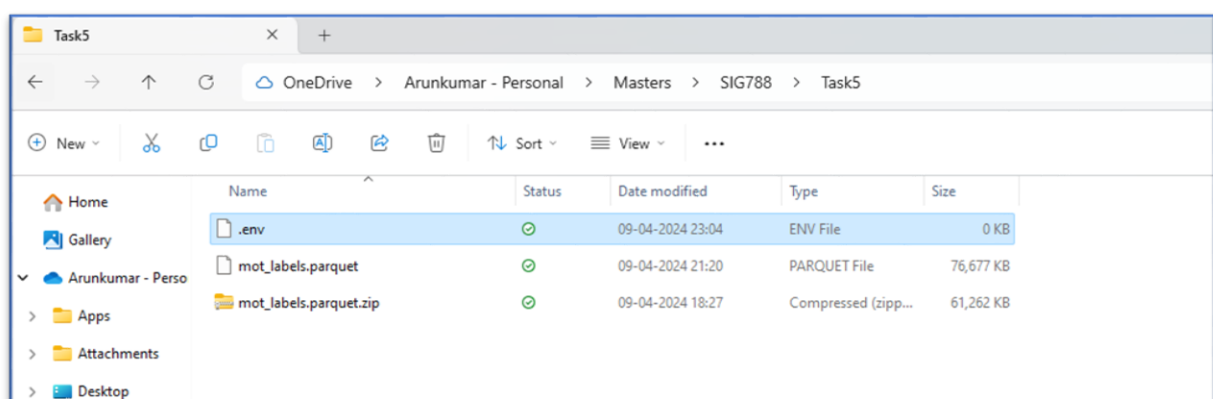
 **python-dotenv:** This package reads key-value pairs from a .env file and sets them as environment variables, enhancing the security and flexibility of application's configuration management.

### Configure .env file:

For Azure Computer Vision services, follow these steps to enhance security:

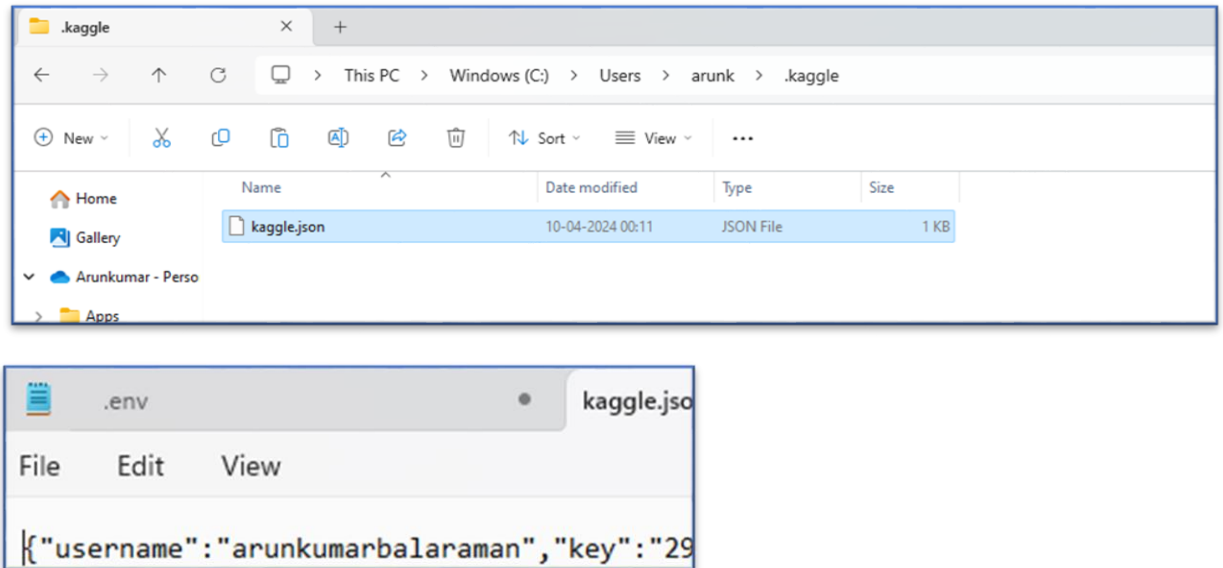
-  After deployment, copy Key1 (**subscription\_Key**) and the **endpoint**.
-  Paste these into a **.env** file in working directory.
-  These will be assigned as environment variables and can be read directly in Python code.

This method ensures **subscription\_key**, **endpoint** and **resource ID** are not displayed to users, enhancing the security of application. Please refer to the snapshot of the **.env** file.



### Setting up Kaggle folder:

The Kaggle.json file is used to interact with Datasets to download data, in this case we would be using to download the videos.



### Selecting 3 Videos for training Images:

Import the necessary libraries in Python SDK:

```
# to connect to the training resource
from azure.cognitiveservices.vision.customvision.training import
CustomVisionTrainingClient

# to connect to the prediction resource
from azure.cognitiveservices.vision.customvision.prediction import
CustomVisionPredictionClient

# to send the input files in batch; and to identify the object regions; for the training of the
model.
from azure.cognitiveservices.vision.customvision.training.models import
ImageFileCreateBatch, ImageFileCreateEntry, Region

# To authenticate the client
from msrest.authentication import ApiKeyCredentials
import os, uuid

# To read the local environment variables and secret keys
import os, dotenv
from dotenv import load_dotenv, find_dotenv

# To read the dataset
import pandas as pd
```

```
# to view images
from IPython.display import Image as img

# to process data in batches
import itertools

# to draw bounding boxes in local output.
from PIL import Image, ImageDraw
import matplotlib.pyplot as plt
import numpy as np

# Unzip file
import zipfile

# Set os
import os
```

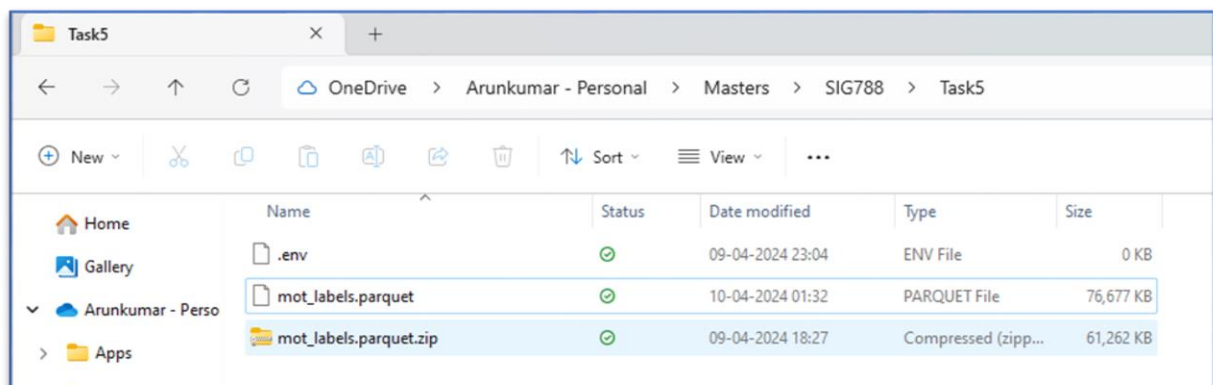
### Setting up Working directory:

```
# Setting Working Directory
os.chdir(r'C:\Users\arunk\OneDrive\Masters\SIG788\Task5')
print(os.getcwd())
```

```
# Setting Working Directory
os.chdir(r'C:\Users\arunk\OneDrive\Masters\SIG788\Task5')
print(os.getcwd())

C:\Users\arunk\OneDrive\Masters\SIG788\Task5
```

### Downloaded Parquet file from Kaggle:



Name	Status	Date modified	Type	Size
.env	✓	09-04-2024 23:04	ENV File	0 KB
<b>mot_labels.parquet</b>	✓	10-04-2024 01:32	PARQUET File	76,677 KB
mot_labels.parquet.zip	✓	09-04-2024 18:27	Compressed (zip...)	61,262 KB

The Parquet file has been downloaded and its been zipped in below code. This file will be used to identify the videos to extract frame and apply bounding boxes information available in this dataset.

### Code:

```
# Assign Zip file
zip_file_path = './mot_labels.parquet.zip'
unzipped_folder_path = os.getcwd()
```

```

# Unzipping the .parquet.zip file
with zipfile.ZipFile(zip_file_path, 'r') as zip_ref:
    zip_ref.extractall(unzipped_folder_path)

# .parquet file
parquet_file_path = 'mot_labels.parquet'

# Loading the .parquet file
df = pd.read_parquet(parquet_file_path)

# Display the first 5 rows
df.head()

```

**Output:**

# Display the first 5 rows  
df.head()

Out[3]:

	name	videoName	frameIndex	id	category	attributes.crowd	attributes.occluded	attributes.truncated	box2d.x1	box2d.x2	box2d.y1	t
0	01c71072-718028b8-0000001.jpg	01c71072-718028b8	0	00089537	car	False	True	False	825.173210	1003.094688	355.011547	411
1	01c71072-718028b8-0000001.jpg	01c71072-718028b8	0	00089538	car	False	True	False	484.295612	700.461894	346.697460	42
2	01c71072-718028b8-0000001.jpg	01c71072-718028b8	0	00089539	pedestrian	False	True	False	645.588915	663.879908	338.383372	35
3	01c71072-718028b8-0000001.jpg	01c71072-718028b8	0	00089540	car	False	False	False	120.969977	192.471132	359.168591	40
4	01c71072-718028b8-0000001.jpg	01c71072-718028b8	0	00089541	car	False	False	False	251.501155	315.519630	354.180139	40

**Inference on dataset:**

The dataset from various videos has been included in Kaggle which would specifically help us in object detection. The dataset includes annotated frames with details about the presence and position of objects like cars, pedestrians, bus, cycle, etc. Each object is assigned a unique ID and category.

**Key columns in the dataset:**

- **Bounding Box Coordinates:** They are
  - box2d.x1, box2d.x2 for horizontal positioning and
  - box2d.y1, box2d.y2 for vertical positioning helping in precise object localization.

**Top 3 Videos**

In the dataset, identifying the 3 videos with a more number of categories by performing a group by count on VideoName and category. This helps in selecting the top 3 video when car, bus and bicycle has more occurrence for better training.

**Code:**

```

# Define a list to store top videos
top_3_videos = []

# Iterate over each category
for category in ['bicycle', 'bus', 'car']:
    # Filter the DataFrame
    filtered_df = df[(df['attributes.crowd'] == False) & (df['attributes.occluded'] == False) &
(df['category'] == category)]

    # Group by 'videoName' and count occurrences of the category
    category_counts = filtered_df.groupby('videoName').size()

    # Find the top video and its count
    top_video = category_counts.idxmax()
    top_count = category_counts.max()

    # Print results
    print("Top video for", category, ":", top_video)
    print(category, "count:", top_count)

    # Add top video to the list
    top_3_videos.append((top_video, top_count))

# Sort top videos based on count in descending order
top_3_videos.sort(key=lambda x: x[1], reverse=True)

# Display the top 3 videos
print("\nTop 3 Videos:")
for i, (video, count) in enumerate(top_3_videos[:3], 1):
    print("{} Video: {}, Count: {}".format(i, video, count))

```

**Output:**

```

print("\nTop 3 Videos:")
for i, (video, count) in enumerate(top_3_videos[:3], 1):
    print("{} Video: {}, Count: {}".format(i, video, count))

Top video for bicycle : 00fcfec9-7ba5dabf
bicycle count: 203
Top video for bus : 027e72be-8b4f222c
bus count: 225
Top video for car : 014f61f0-c93a2f84
car count: 1405

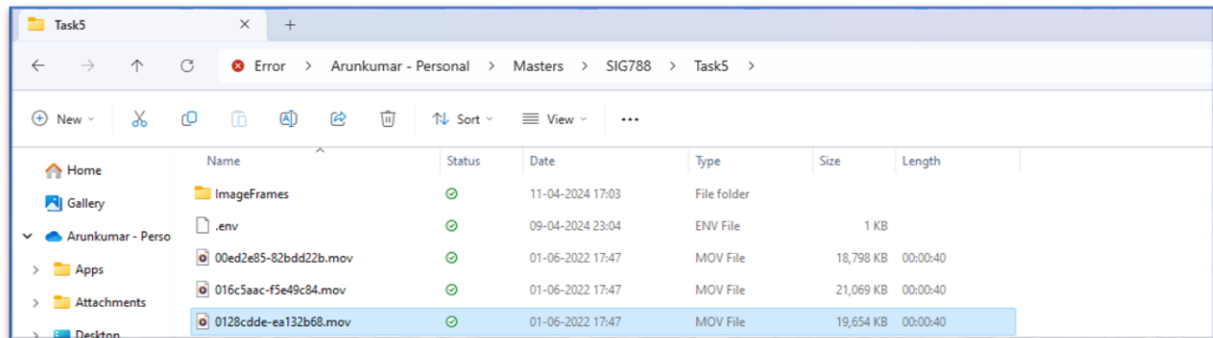
Top 3 Videos:
1. Video: 014f61f0-c93a2f84, Count: 1405
2. Video: 027e72be-8b4f222c, Count: 225
3. Video: 00fcfec9-7ba5dabf, Count: 203

: topvideos = [video[0] for video in top_3_videos]
topvideos

: ['014f61f0-c93a2f84', '027e72be-8b4f222c', '00fcfec9-7ba5dabf']

```

Manually downloaded these videos to extract frame images as I don't want to download all 1000 images where the file size is 20 GB.



The training frame images would be picked up only from these three videos hence restricting the dataset to information only for these three videos.

```
# Restricting the datasets to only three videos
restricteddata = df.query('videoName in @topvideos').reset_index(drop=True).copy()
restricteddata.head()
```

Output:

```
# Restricting the datasets to only three videos
restricteddata = df.query('videoName in @topvideos').reset_index(drop=True).copy()
restricteddata.head()
```

	name	videoName	frameIndex	id	category	attributes.crowd	attributes.occluded	attributes.truncated	box2d.x1	box2d.x2	box2d.y1	box2d.y2
0	00fcfec9-7ba5dabf-0000001.jpg	00fcfec9-7ba5dabf	0	00065944	truck	False	False	False	313.591160	1054.806630	26.519337	685.000000
1	00fcfec9-7ba5dabf-0000001.jpg	00fcfec9-7ba5dabf	0	00065945	car	False	True	False	65.635359	328.176796	437.569061	584.000000
2	00fcfec9-7ba5dabf-0000001.jpg	00fcfec9-7ba5dabf	0	00065946	car	False	False	True	0.662983	133.504409	458.784530	652.000000
3	00fcfec9-7ba5dabf-0000001.jpg	00fcfec9-7ba5dabf	0	00065947	car	False	True	False	287.071823	366.629834	434.917127	522.000000
4	00fcfec9-7ba5dabf-0000002.jpg	00fcfec9-7ba5dabf	1	00065944	truck	False	False	False	313.591160	1054.806630	26.470227	685.000000

Category – Tagging

Now let's restrict the data further into top 6 category for performing training from these videos.

```
# Picking top 6 categories for these images
Top6category = restricteddata['category'].value_counts().head()
Top6category
```

Output

```
# Picking top 6 categories for these images
top6category = restricteddata['category'].value_counts().head(6)
top6category
```

car	2931
pedestrian	911
truck	568
bicycle	512
rider	308
bus	269

Name: category, dtype: int64

The top 6 categories are Car, pedestrian, bicycle, truck, bus & rider are most frequent in these videos and tagging the images with these categories.

Deleting other categories from the dataset.

```
# creating list of 6 categories
cat_list = top6category.index.to_list()
print(cat_list)

# restrict dataset further to 5 categories
restricteddata = restricteddata.query('category in @cat_list').copy()
restricteddata['category'].value_counts()
```

**Output:**

```
# creating list of 6 categories
cat_list = top6category.index.to_list()
print(cat_list)

# restrict dataset further to 5 categories
restricteddata = restricteddata.query('category in @cat_list').copy()
restricteddata['category'].value_counts()

['car', 'pedestrian', 'truck', 'bicycle', 'rider', 'bus']

car      2931
pedestrian  911
truck      568
bicycle    512
rider      308
bus        269
Name: category, dtype: int64
```

Video conversion mov to mp4:

Converting .mov to .mp4 for Azure Custom Vision ensures consistency and avoids potential errors during model training or inference. The .mp4 format is widely supported and playable on various devices and platforms, enhancing the versatility and accessibility of the model.

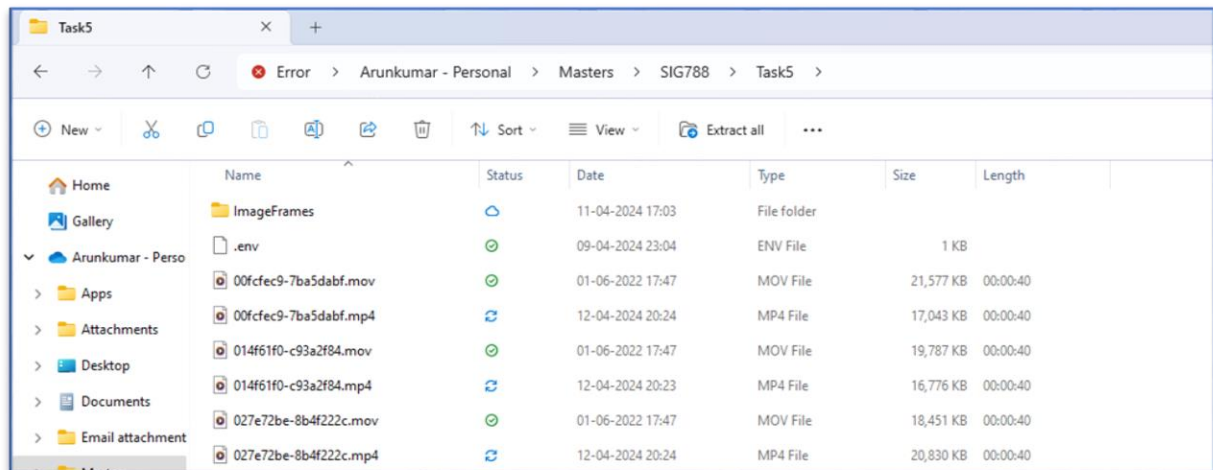
**Code:**

```
# Loop the top 3 videos
for video_file in topvideos:
    (
        ffmpeg
        .input(video_file + '.mov')
        .output(video_file + '.mp4')
        .global_args('-y') # overwrite .mp4 if available
        .run()
    )
# Print success
print(f"Converted {video_file + '.mov'} to {video_file + '.mp4'}")
```

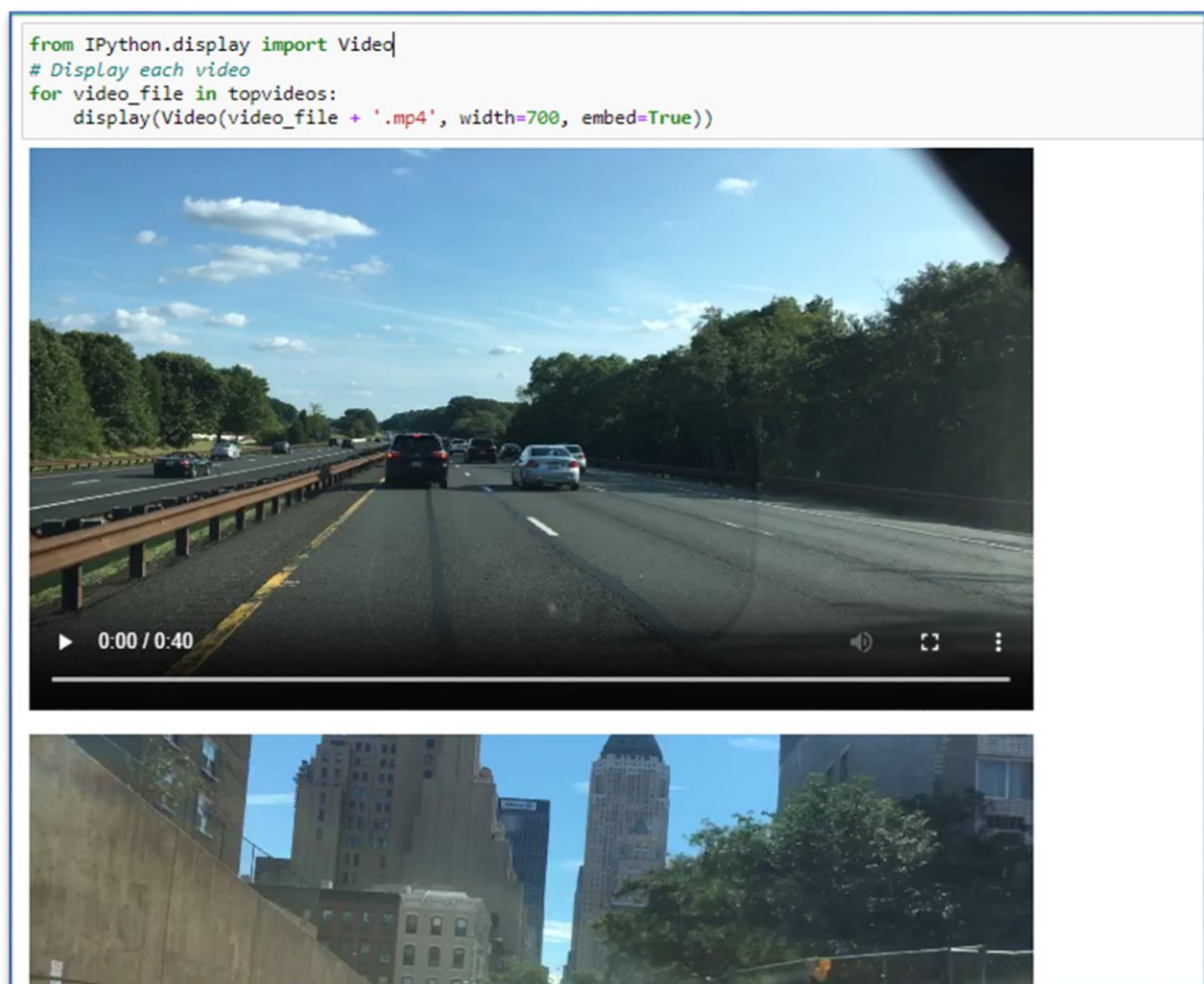
**Output:**

```
Converted 014f61f0-c93a2f84.mov to 014f61f0-c93a2f84.mp4
Converted 027e72be-8b4f222c.mov to 027e72be-8b4f222c.mp4
Converted 00fcfec9-7ba5dabf.mov to 00fcfec9-7ba5dabf.mp4
```





Successfully converted the .mov into .mp4 files and now let's proceed to display the .mp4 format using `lpython.display`



Frame image calculation and selection:

Let's calculate the frame in video against frame in the datasets.

```
# Initialize a list
```

```

video_frames_info = []

# Loop through each video to get frame counts
for video in topvideos:
    cap = cv2.VideoCapture(video + '.mp4')
    if not cap.isOpened():
        print(f"Failed to open video: {video + '.mp4'}")
        num_frames = 0
        fps = 0
    else:
        fps = cap.get(cv2.CAP_PROP_FPS)
        num_frames = int(cap.get(cv2.CAP_PROP_FRAME_COUNT))
    cap.release()

    video_frames_info.append({
        'videoName': video,
        'fps': fps,
        'num_frames': num_frames
    })

# Convert to DataFrame
video_frames_df = pd.DataFrame(video_frames_info)

# Group by 'videoName' to get the max frame index for each video
max_frame_indices = restricteddata[['frameIndex',
'videoName']].groupby('videoName').max().reset_index()

# Merge the two DataFrames on 'videoName' to compare
comparison_df = pd.merge(video_frames_df, max_frame_indices, how='left',
on='videoName', suffixes=('_actual', '_dataset'))

# comparison DataFrame
comparison_df

```

**Output:**

```
# comparison DataFrame
comparison_df
```

	videoName	fps	num_frames	frameIndex
0	014f61f0-c93a2f84	29.97003	1201	201
1	027e72be-8b4f222c	29.97003	1202	201
2	00fcfec9-7ba5dabf	29.97003	1206	202

**Inference:**

Compared three videos with varying **frame rates** and **total frames**.

- All three videos has a frame rate of 30 FPS. The total number of frames varies significantly among the videos due to differences in video length and frame rate.

The **maximum frame index** in dataset is **notably lower** than the actual number of frames for each video, indicating that the dataset **might not encompass** the full length of the videos. This suggests that only a subset of each video's frames is used, possibly due to relevance or **dataset incompleteness**.

To **overcome** this **limitation**, an integer value obtained by **dividing** the **actual video frames** by the **dataset's frame index** is used to capture frame images at specific points.

**Code:**

```
# Loop for each video
for index, row in comparison_df.iterrows():
    video_name = row['videoName'] # Video Name
    num_frames = row['num_frames'] # Num of frames in Video
    max_frame_index = row['frameIndex'] # Max frames in dataset

    # Calculate the adjustment factor for each video
    adjustment_factor = num_frames / max_frame_index

    # Update frameIndex in video_labels where videoName matches
    restricteddata.loc[restricteddata['videoName'] == video_name, 'adjusted_frameIndex'] = (
        restricteddata.loc[restricteddata['videoName'] == video_name, 'frameIndex'] *
        adjustment_factor
    ).round().astype(int)

# Checking for Null values in new column
restricteddata['adjusted_frameIndex'].isna().sum()
```

**Output:**

```
# Checking for Null values in new column
restricteddata['adjusted_frameIndex'].isna().sum()

0
```

Basic check the new column `adjusted_frameIndex` to match the video

restricteddata.tail()											
x	id	category	attributes.crowd	attributes.occluded	attributes.truncated	box2d.x1	box2d.x2	box2d.y1	box2d.y2	haveVideo	adjusted_frameIndex
9	00038846	truck	False	False	False	508.340215	588.009909	327.002477	429.26507	True	1190.0
0	00038850	pedestrian	False	False	False	371.593724	406.077622	365.053675	426.88687	True	1196.0
0	00038846	truck	False	False	False	509.529315	589.199009	327.002477	429.26507	True	1196.0
1	00038850	pedestrian	False	False	False	372.782824	408.455822	366.242775	426.88687	True	1202.0
1	00038846	truck	False	False	False	509.529315	589.199009	327.002477	429.26507	True	1202.0

As we now successfully created the `adjusted_frameIndex`, let's proceed to create the frame images and save it a folder to load the images into Azure custom vision for model training.

### Create Frame Image:

We will utilize the adjusted frame index from the dataset for each video to generate images, which will be stored in a designated folder. Subsequently, employed Python SDK to verify the precision of the bounding boxes. The images, along with the bounding box data, will then be uploaded to the Azure Custom Vision project for further analysis.

Selecting 33 random frames to save image in output folder for each Video Name.

```
# 33 random frames per video
def select_random_frames(frames, count=33):
    if len(frames) > count:
        return np.random.choice(frames, size=count, replace=False)
    return frames

unique_frames_per_video =
restricteddata.groupby('videoName')['adjusted_frameIndex'].unique().apply(lambda x:
select_random_frames(np.sort(x)))

# Function to read the frame index from dataframe and save image
def save_specific_frame(video_path, frame_number, output_filename):
    cap = cv2.VideoCapture(video_path)
    cap.set(cv2.CAP_PROP_POS_FRAMES, frame_number)
    success, frame = cap.read()
    if success:
        cv2.imwrite(output_filename, frame)
    cap.release()

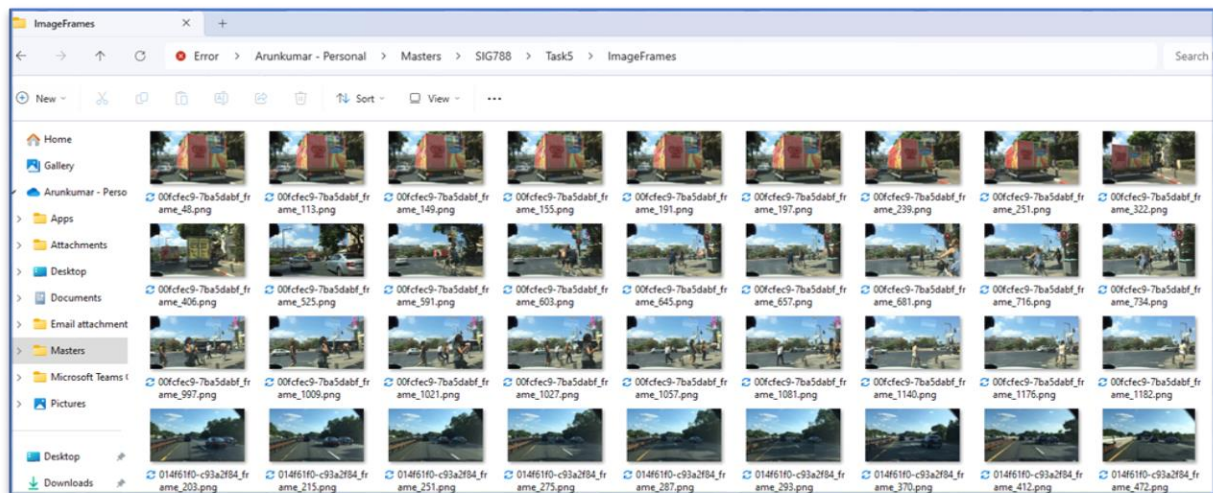
# Image directory
image_directory = 'ImageFrames'
if not os.path.exists(image_directory):
    os.makedirs(image_directory)

# Loop for each item
for video_name, frames in unique_frames_per_video.items():
    video_path = video_name + '.mp4'
    for frame_number in frames:
        output_filename = os.path.join(image_directory,
f'{video_name}_frame_{int(frame_number)}.png')
        save_specific_frame(video_path, frame_number, output_filename)

# List unique_frames_per_video
selected_frames = [(video_name, frame) for video_name, frames in
unique_frames_per_video.items() for frame in frames]

# Frame selection
filtered_dataset = restricteddata[restricteddata.apply(lambda row: (row['videoName'],
row['adjusted_frameIndex']) in selected_frames, axis=1)].reset_index(drop=True)
```

99 images are saved in the below path to load the same into Azure Custom Vision project.



As we now saved the images, let's display 2 images for each video name to ensure the bounding boxes are correctly aligned to train the images in Custom vision project.

```
# function to display the saved images with bounding boxes
def display_image_with_annotations(image_path, annotations):
    """
    Displays an image with bounding boxes and category labels.

    Parameters:
    - image_path: Path to the image file.
    - annotations: DataFrame containing bounding box and category information.
    """
    # Load the image
    img = Image.open(image_path)

    # Create a figure
    fig, ax = plt.subplots(1, figsize=(12, 8))
    ax.imshow(img)

    # Draw bounding boxes and labels
    for _, row in annotations.iterrows():
        x1, y1, x2, y2 = row['box2d.x1'], row['box2d.y1'], row['box2d.x2'], row['box2d.y2']
        width, height = x2 - x1, y2 - y1
        rect = patches.Rectangle((x1, y1), width, height, linewidth=1, edgecolor='r',
                                facecolor='none')
        ax.add_patch(rect)
        ax.text(x1, y1, row['category'], color='white', backgroundcolor='red')

    plt.show()
```

```
# Loop to run to display 2 images per video file
for video_name in filtered_dataset['videoName'].unique():
    # Filter the dataset for this videoName
    video_data = filtered_dataset[filtered_dataset['videoName'] == video_name]
```



```

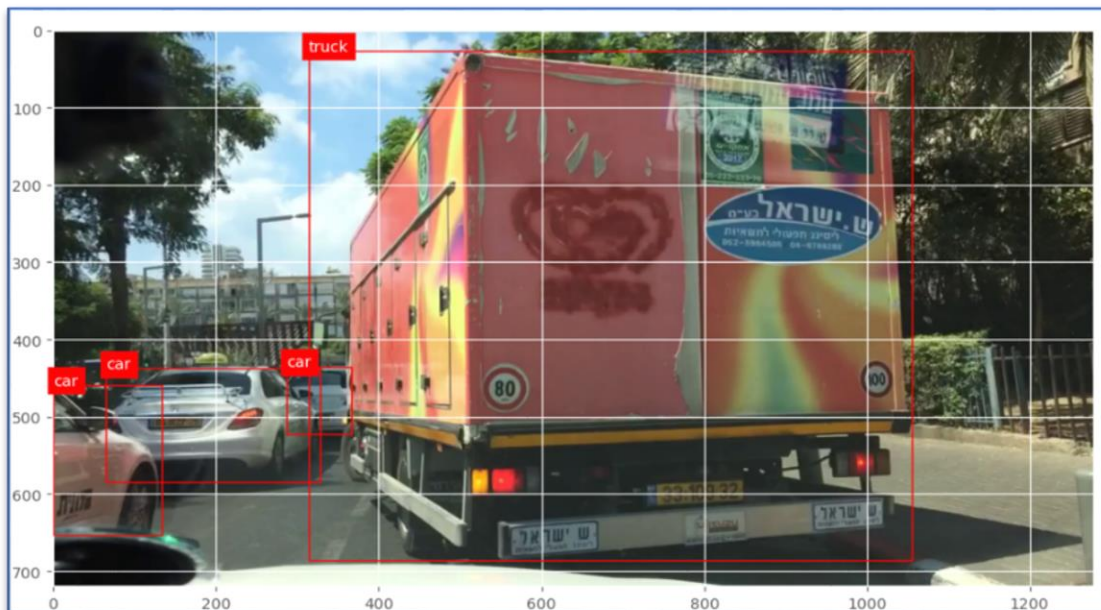
# Get two unique frames
unique_frames = video_data['adjusted_frameIndex'].unique()[1:2]

for frame in unique_frames:
    # Filter annotations for selected frame
    frame_annotations = video_data[video_data['adjusted_frameIndex'] == frame]

    # Image filename
    image_filename = f"{video_name}_frame_{int(frame)}.png"
    image_path = os.path.join(image_directory, image_filename)

    # Display the image with annotations
    display_image_with_annotations(image_path, frame_annotations)

```

**Output:**

As we now validated the bounding boxes are correctly assigned, now let's loaded the images into Azure custom vision project.

#### Azure Custom Vision Project Image Load:

As we have validated the images with bounding boxes, we will start to set up the environment variables for the key, subscription and endpoint for both train and prediction.

```
# Read the environment file to access secret keys
load_dotenv()

# Replace with valid values
VISION_TRAINING_ENDPOINT = os.environ["VISION_TRAINING_ENDPOINT"]
training_key = os.environ["VISION_TRAINING_KEY"]
prediction_key = os.environ["VISION_PREDICTION_KEY"]
prediction_resource_id = os.environ["VISION_PREDICTION_RESOURCE_ID"]
VISION_PREDICTION_ENDPOINT= os.environ["VISION_PREDICTION_ENDPOINT"]
```

#### Project Creation:

```
# create variables for training resource
credentials = ApiKeyCredentials(in_headers={"Training-key": training_key})
trainer = CustomVisionTrainingClient(VISION_TRAINING_ENDPOINT, credentials)

# create variables for prediction resource
prediction_credentials = ApiKeyCredentials(in_headers={"Prediction-Key": prediction_key})
predictor = CustomVisionPredictionClient(VISION_PREDICTION_ENDPOINT,
prediction_credentials)

publish_iteration_name = "VehicleDetection"

# Find the object detection domain
obj_detection_domain = next(domain for domain in trainer.get_domains() if
                             domain.type == "ObjectDetection" and domain.name == "General")

# Create a new project
print("Creating project...")
# Use uuid to avoid project name collisions.
project =
trainer.create_project(publish_iteration_name, domain_id=obj_detection_domain.id)
# Created
print("Created...")
```

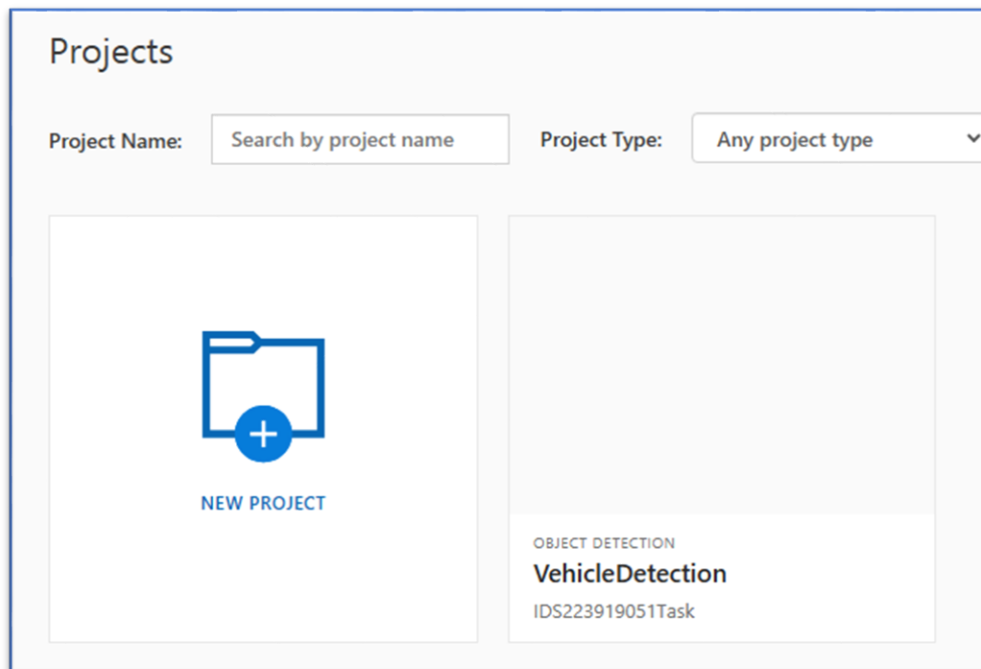
#### Output:

```
# Created
print("Created...")

Creating project...
Created...

In [20]: predictor
Out[20]: <azure.cognitiveservices.vision.customvision.prediction._custom_vision_prediction_client.CustomVisionPredictionClient at 0x17780b1ff90>
```

The project Vehicle detection has been successfully created in Azure custom vision platform using Python SDK.



Let's now condense the data into a single row per image. Since an image contains multiple objects represented as rows, we'll create dictionary records for categories and bounding box information to consolidate the data.

```
# Function to aggregate categories and corresponding boxes together
def aggregate_categories_and_boxes(group):
    categories_boxes = []
    for _, row in group.iterrows():
        categories_boxes.append({
            'category': row['category'],
            'box': {'x1': row['box2d.x1'], 'y1': row['box2d.y1'], 'x2': row['box2d.x2'], 'y2':
row['box2d.y2']}
        })
    return categories_boxes

# Group by 'videoName' and 'adjusted_frameIndex', then apply the aggregation function
aggregated_data = filtered_dataset.groupby(['videoName',
'adjusted_frameIndex']).apply(aggregate_categories_and_boxes).reset_index(name='categories_boxes')

# aggregated data head
aggregated_data.head()
```



output:

	videoName	adjusted_frameIndex	categories_boxes
0	00fcfec9-7ba5dabf	30.0	[{'category': 'truck', 'box': {'x1': 313.37016...
1	00fcfec9-7ba5dabf	48.0	[{'category': 'truck', 'box': {'x1': 312.70718...
2	00fcfec9-7ba5dabf	137.0	[{'category': 'truck', 'box': {'x1': 312.26519...
3	00fcfec9-7ba5dabf	143.0	[{'category': 'truck', 'box': {'x1': 312.92817...
4	00fcfec9-7ba5dabf	185.0	[{'category': 'truck', 'box': {'x1': 313.59116...

Normalization:

We performed normalization of the x1, x2, y1, & y2 to ensure:

- **Coordinate System Compatibility:** Normalizing bounding box coordinates to a standard range ensures compatibility across different systems and platforms, and meets the expectations of object detection models.
- **Scale Invariance:** Normalization ensures consistent object treatment across varying image resolutions, enhancing model robustness by focusing on the object's relative space in the image.
- **Flexibility and Generalization:** Normalization enables flexible model operation across different deployment environments and improves model generalization, enhancing performance on real-world tasks.
- **Efficient Training:** Normalization simplifies the learning process by reducing coordinate value ranges and maintains stable gradients during training, preventing issues like exploding or vanishing gradients.

```
# Normalize the x1, x2, y1, y2
def normalize_box(box, image_width=1280, image_height=720):

    return {
        "left": box['x1'] / image_width,
        "top": box['y1'] / image_height,
        "width": (box['x2'] - box['x1']) / image_width,
        "height": (box['y2'] - box['y1']) / image_height,
    }
```

Upload Images:

```
def upload_image(row):
    image_filename = f"{row['videoName']}_frame_{int(row['adjusted_frameIndex'])}.png"
    image_path = os.path.join('ImageFrames', image_filename)

    if not os.path.exists(image_path):
        print(f"File not found: {image_path}")
        return

    regions = []
```

```

for cb in row['categories_boxes']:
    category = cb['category']
    box = cb['box']

    if category not in tags_cache:
        # Create tag if not in cache and update the cache
        created_tag = trainer.create_tag(project.id, category)
        tags_cache[category] = created_tag.id

    tag_id = tags_cache[category]
    normalized_box = normalize_box(box)

    regions.append(Region(tag_id=tag_id, left=normalized_box['left'],
top=normalized_box['top'], width=normalized_box['width'],
height=normalized_box['height']))

    with open(image_path, "rb") as image_contents:
        tagged_images_with_regions = [ImageFileCreateEntry(name=image_filename,
contents=image_contents.read(), regions=regions)]

    upload_result = trainer.create_images_from_files(project.id,
ImageFileCreateBatch(images=tagged_images_with_regions))

    if not upload_result.is_batch_successful:
        print(f"Failed to upload image: {image_filename}")
        for image in upload_result.images:
            print("Image status: ", image.status)
    else:
        print(f"Successfully uploaded {image_filename} with regions.")

```

```

# Cache existing tags to avoid duplication errors
tags_cache = {tag.name: tag.id for tag in trainer.get_tags(project.id)}

# Apply the function to each row of the DataFrame
aggregated_data.apply(upload_image, axis=1)

print("Image upload to Azure Custom Vision is complete.")

```

**Output:**

```

# Cache existing tags to avoid duplication errors
tags_cache = {tag.name: tag.id for tag in trainer.get_tags(project.id)}

# Apply the function to each row of the DataFrame
aggregated_data.apply(upload_image, axis=1)

print("Image upload to Azure Custom Vision is complete.")

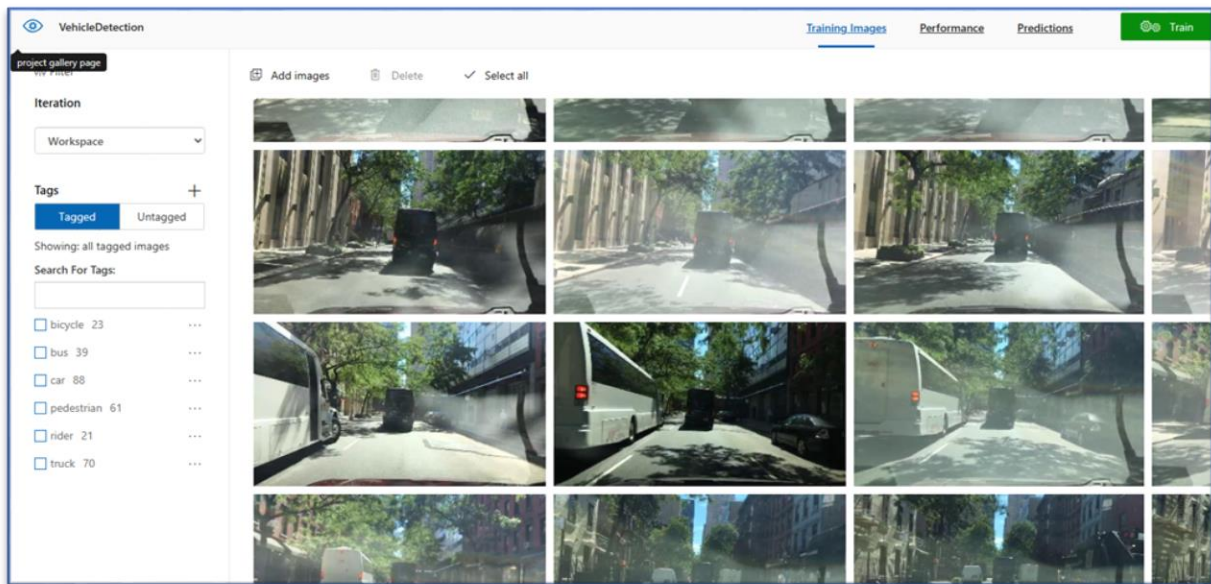
Successfully uploaded 00fcfec9-7ba5dabf_frame_0.png with regions.
Successfully uploaded 00fcfec9-7ba5dabf_frame_6.png with regions.
Successfully uploaded 00fcfec9-7ba5dabf_frame_12.png with regions.
Successfully uploaded 00fcfec9-7ba5dabf_frame_18.png with regions.

```

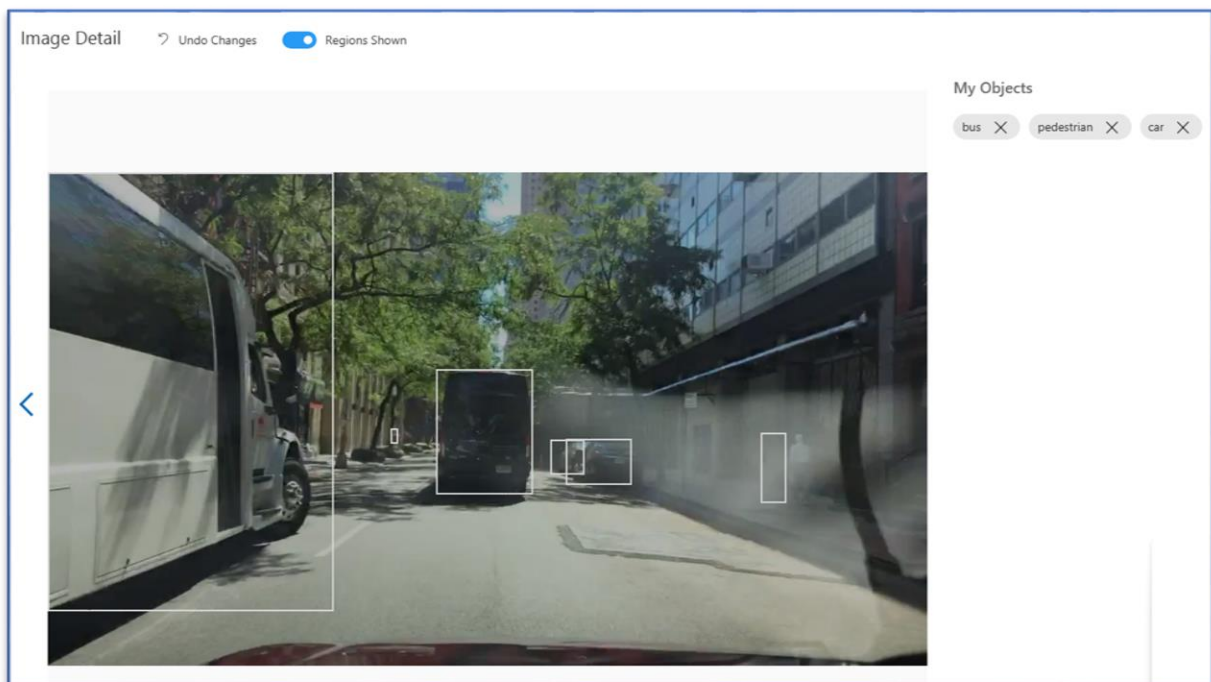
**Inference:**

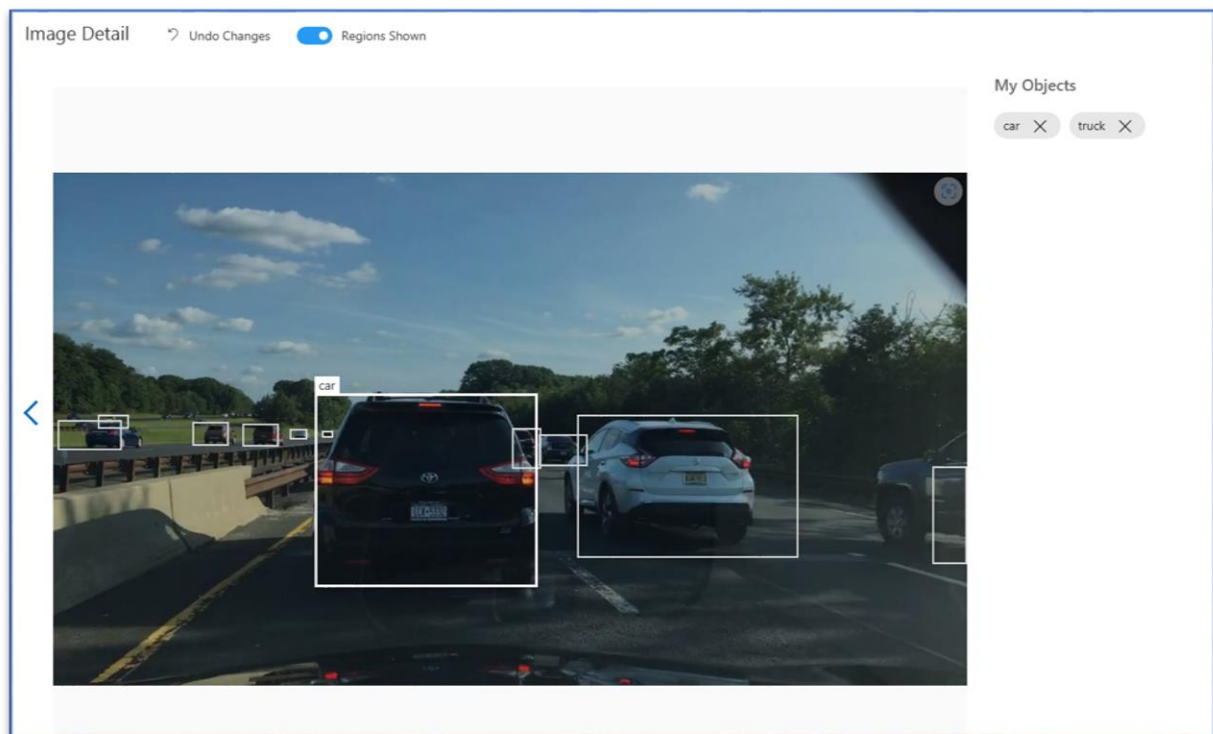
Loaded all the 99 images with its region and tag name information for the Azure custom vision project for the training of the model with the 6 categories

1. Bicycle
2. Car
3. Pedestrian
4. Truck
5. Bus
6. rider



Validating images in Portal:  
**Image 1 with region and tags.**



**Image2 with region and tags.**

As we now successfully loaded the image along with region and tag name to Azure custom vision project, let's proceed with training.

**Training:**

```
import time

print ("Training...")
iteration = trainer.train_project(project.id)
while (iteration.status != "Completed"):
    iteration = trainer.get_iteration(project.id, iteration.id)
    print ("Training status: " + iteration.status)
    time.sleep(1)
```

**Output:**

```
: import time

print ("Training...")
iteration = trainer.train_project(project.id)
while (iteration.status != "Completed"):
    iteration = trainer.get_iteration(project.id, iteration.id)
    print ("Training status: " + iteration.status)
    time.sleep(1)

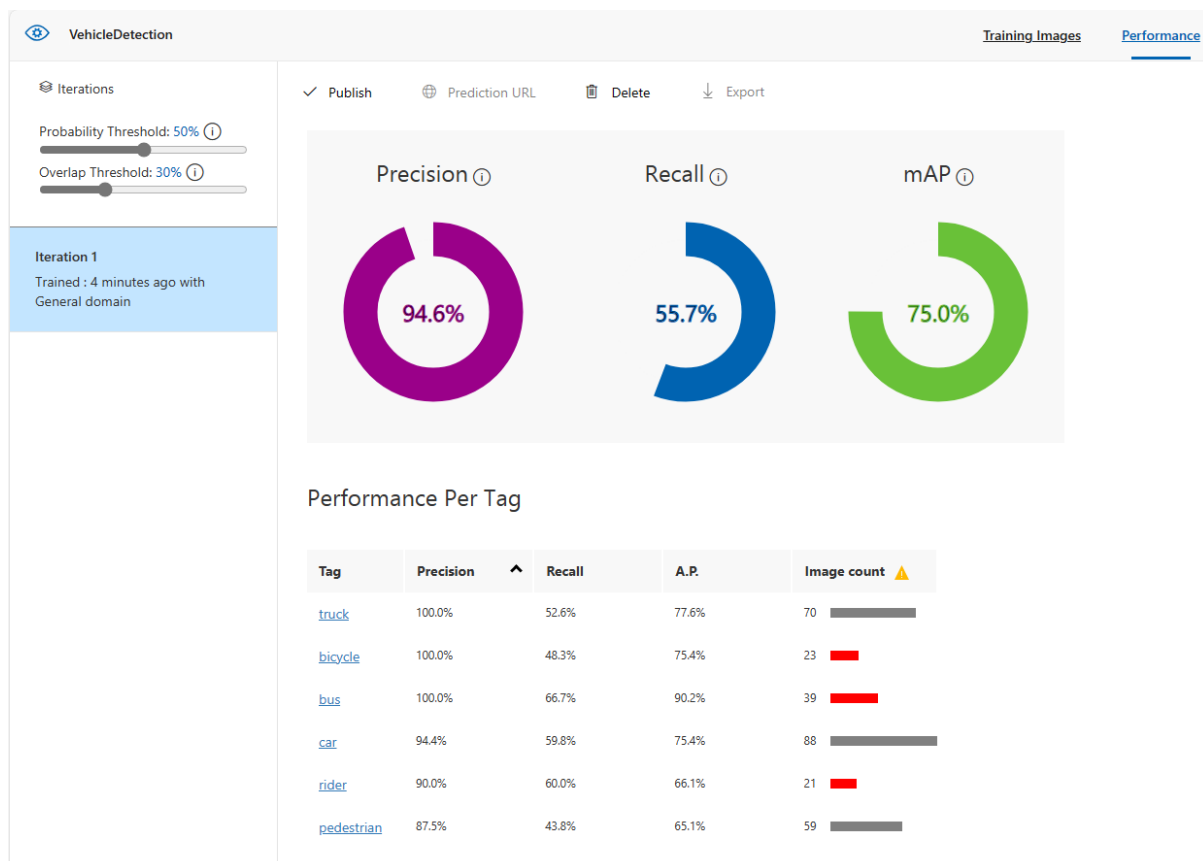
Training...
Training status: Training
Training status: Training
Training status: Training
Training status: Training
Training status: Training
Training status: Training
```

- **Initiate Training:** The ``trainer.train_project(project.id)`` command starts the model training using the uploaded images and tags.
- **Polling for Status:** A while loop checks the training status continuously. The ``trainer.get_iteration(project.id, iteration.id)`` retrieves the current training iteration and prints the status.
- **Waiting for Completion:** The ``time.sleep(1)`` command pauses the script for a second before checking the status again, preventing excessive server requests.
- **Completion:** Once the iteration status is 'Completed', the loop exits, indicating the end of training. The model is then ready for testing or predictions.

### Performance:

Below are the performance metrics in which the model would be evaluated.

- **Intersection over Union (IoU):** Measures the overlap between the predicted bounding box and the ground truth box to assess localization accuracy.
- **Precision:** The ratio of true positives to the sum of true and false positives, indicating the accuracy of positive predictions.
- **Recall:** The ratio of true positives to the sum of true positives and false negatives, reflecting the model's ability to correctly identify all positives.
- **Mean Average Precision (mAP):** The average of the Average Precision (AP) for each class, providing a score for the model's overall detection accuracy. It uses the ground-truth bounding box and the detected box for calculation.



**Model Performance:****Thresholds:**

- Probability Threshold (50%): The model classifies detections as positive if the confidence level is at least 50%.
- Overlap Threshold (30%): Predicted bounding boxes are considered true positives if they overlap at least 30% with the ground truth.

**Performance Metrics:**

- Precision (94.6%): The model's predictions are 94.6% accurate.
- Recall (55.7%): The model identifies 55.7% of all actual tags.
- mAP (75.0%): The model has a good balance of precision and recall across different classes.

**Performance Per Tag:**

- Truck: Precision is 100%, recall is 52.6%, AP is 77.6%, and image count is 70.
- Bicycle: Precision is 100%, recall is 48.3%, AP is 75.4%, and image count is 23 (red bar).
- Bus: Precision is 100%, recall is 66.7%, AP is 90.2%, and image count is 39 (red bar).
- Car: Precision is 94.4%, recall is 59.8%, AP is 75.4%, and image count is 88.
- Rider: Precision is 90.0%, recall is 60.0%, AP is 66.1%, and image count is 21 (red bar).
- Pedestrian: Precision is 87.5%, recall is 43.8%, AP is 65.1%, and image count is 59.

**Image Count Imbalance:**

- The red bars for 'bicycle', 'bus', and 'rider' indicates an imbalanced or insufficient dataset for these classes.

**Conclusion:**

The model exhibits high precision across all tags, but the recall rates are significantly lower, indicating missed true positives. This is especially evident for 'bicycle', 'bus', and 'rider' tags, which have fewer images in the dataset. The overall mAP score of 75.0% suggests a moderate balance of precision and recall. However, there's substantial room for improvement while adding more images while working on live projects.

**Limitation:**

The model's performance is constrained by the limited number of images due to the use of a free tier. To avoid exhausting resources on a single project and to preserve them for upcoming projects, the quantity of images is kept minimal. This limitation could potentially affect the model's learning ability, especially for imbalanced classes.

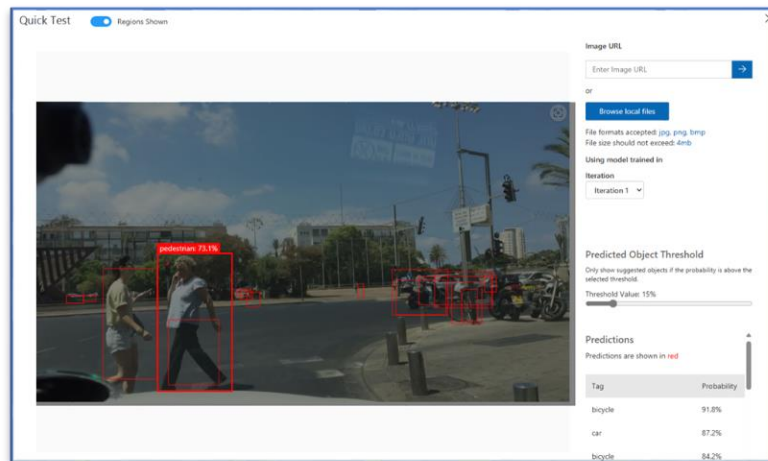


### Improvement Strategies:

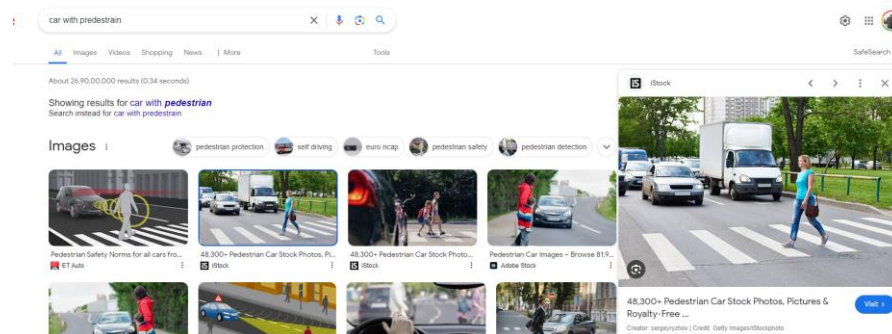
Improvements in recall could be achieved through data augmentation, model tuning, and adding more training data, particularly for underrepresented classes.

### Testing a Sample Image:

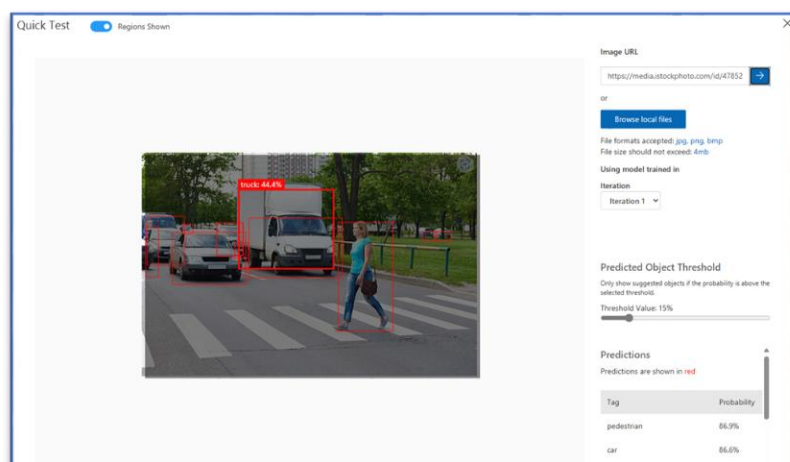
Tested the image using browse file



### Testing a image using web url image



### Testing:



## Test Results:

**Truck Detection:** The model correctly identifies a truck with a confidence of 44.4%. The bounding box accurately encompasses the vehicle.

**Pedestrian Detection:** The model identifies a pedestrian with a high confidence of 86.9%, assuming the bounding box accurately encloses a person.

**Car Detection:** The model identifies a car with a high confidence of 86.6%, provided the bounding box correctly identifies a car in the image.

## Quick Test Insights:

These tests have been conducted on the random web URL image provides an immediate sense of the model's performance on individual instances. However, they may not fully reflect the model's accuracy in a production environment as they are based on single instances rather than a diverse set of test data. Let's publish the model and test the same with a video.

## Publish Model:

Code:

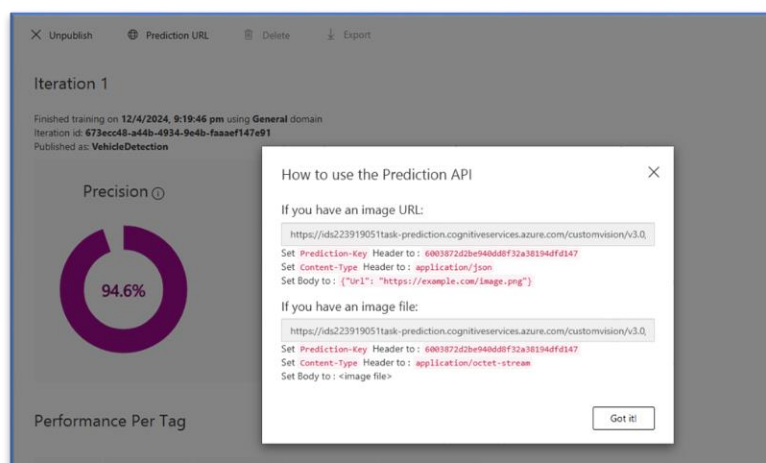
```
# Publish model
# The iteration is now trained. Publish it to the project endpoint
trainer.publish_iteration(project.id, iteration.id, publish_iteration_name,
prediction_resource_id)
print ("Done!")
```

Output:

```
: # Publish model
# The iteration is now trained. Publish it to the project endpoint
trainer.publish_iteration(project.id, iteration.id, publish_iteration_name, prediction_resource_id)
print ("Done!")

Done!
```

## Prediction & Testing:





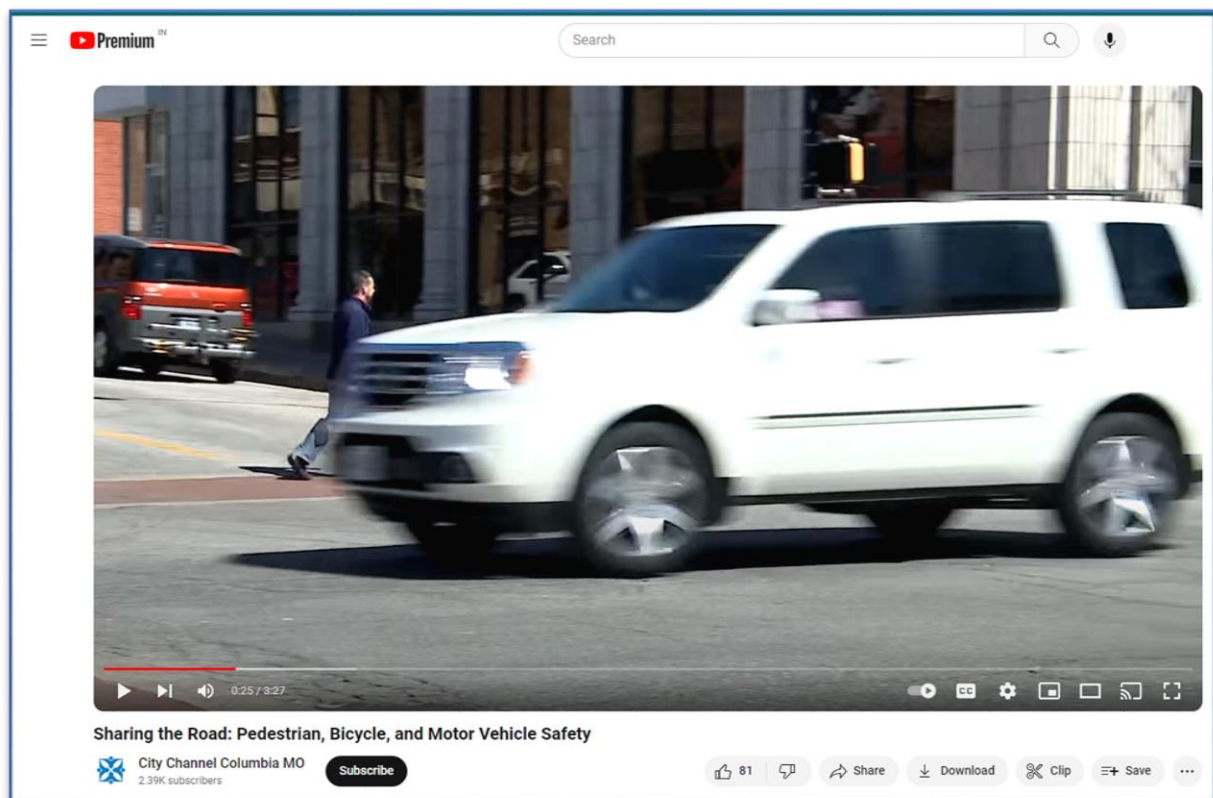
As now we have published the model and created the prediction URL, now let's create the Python SDK to test the prediction URL for the image from local machine by sending a 1 minute video file selected from youtube.

### Youtube Video:

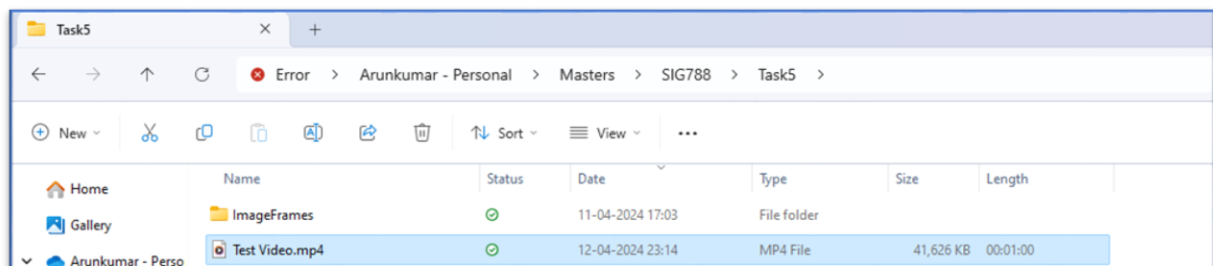
I have selected the below three minutes video for testing the model prediction.

URL: <https://www.youtube.com/watch?v=jj8CfZDPeBs>

### Video Selected:



The video has been downloaded using the link <https://ssyoutube.com/en169ZG/youtube-video-downloader> to the local machine and then used video trimmer from the link [https://online-video-cutter.com/#google\\_vignette](https://online-video-cutter.com/#google_vignette) to trim the video to 1 minute and saved the video as **Test Video.mp4** in the working directory.



Then the test video.mp4 has been sent to the model for the prediction & detecting the object detection.

**Code:**

Function to extract the frame per second.

```
# function to extract frame per second
def extract_frames(video_path, frame_interval):

    # Initialize video capture
    cap = cv2.VideoCapture(video_path)

    # Get the frames per second (fps) of the video
    fps = cap.get(cv2.CAP_PROP_FPS)

    # Initialize frame count
    frame_count = 0

    # Loop through video frames
    while cap.isOpened():
        ret, frame = cap.read() # Read a frame from the video
        if not ret:
            break

        # Check if the current frame number for interval
        if frame_count % int(fps * frame_interval) == 0:
            yield frame

        frame_count += 1 # Increment the frame count

    # Release the video capture object to free resources
    cap.release()
```

Function to send frame to Azure custom vision model using the prediction key and prediction url for the image.

```
# Function to send frame to Azure prediction Api & return Json response
def predict_frame(image, url, prediction_key):

    headers = {
        'Content-Type': 'application/octet-stream', # Indicates that the body contains binary
data.
        'Prediction-Key': prediction_key          # Authentication key required by the API.
    }
    # Sends the POST request to the API.
    response = requests.post(url, headers=headers, data=image)

    # Parses and returns the response as JSON.
    return response.json()
```

Function to draw the bounding boxes and labelling for the predicted image with the given threshold.

```
# function to draw bounding boxes and label to the frame with the probability threshold
```

```

def draw_predictions(frame, predictions, probability_threshold=0.001):

    # loop through the predictions
    for prediction in predictions['predictions']:
        probability = prediction['probability']

        # Only draw predictions with probability
        if probability > probability_threshold:

            # Get the bounding box for the prediction
            bbox = prediction['boundingBox']

            # Get the label for the prediction
            tag = prediction['tagName']

            # Calculate the pixel coordinates of the bounding box
            left = int(bbox['left'] * frame.shape[1])
            top = int(bbox['top'] * frame.shape[0])
            width = int(bbox['width'] * frame.shape[1])
            height = int(bbox['height'] * frame.shape[0])

            # Draw a rectangle around the detected object
            cv2.rectangle(frame, (left, top), (left + width, top + height), (0, 255, 0), 2)

            # Draw the label and probability for bounding box
            label = f"{tag}: {probability:.2f}"
            cv2.putText(frame, label, (left, top - 10), cv2.FONT_HERSHEY_SIMPLEX, 0.5, (0, 255,
0), 2)

    return frame

```

Now let's pass the test video into the model prediction to object detect in the video **one frame per second** to reduce the usage cost in Azure.

```

# Test Video file
video_file = 'Test Video.mp4'

# To read load the prediction URL
load_dotenv()

# Read the prediction URL from environment variables
prediction_url = os.environ["Vision_PREDICTION_URL"]

# Initialize video capture to get video properties
cap = cv2.VideoCapture(video_file)
ret, frame = cap.read()
height, width = frame.shape[:2]
cap.release()

# Initialize VideoWriter to save output

```

```

fourcc = cv2.VideoWriter_fourcc(*'XVID')
out = cv2.VideoWriter('output.avi', fourcc, 1.0, (width, height))

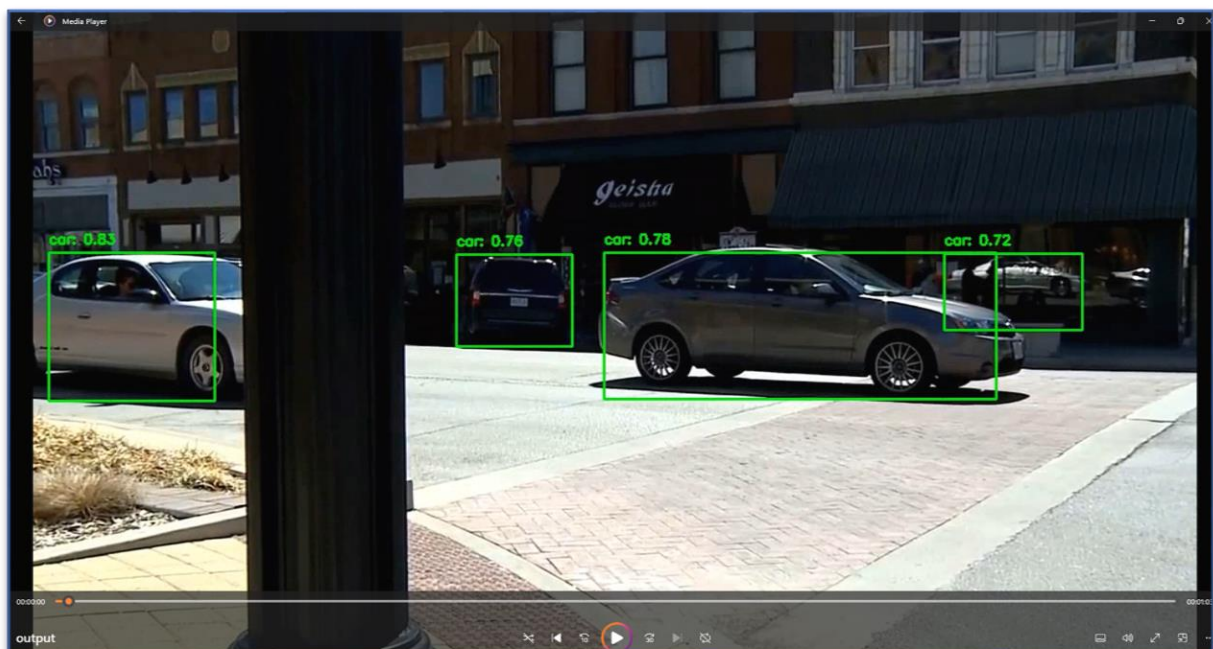
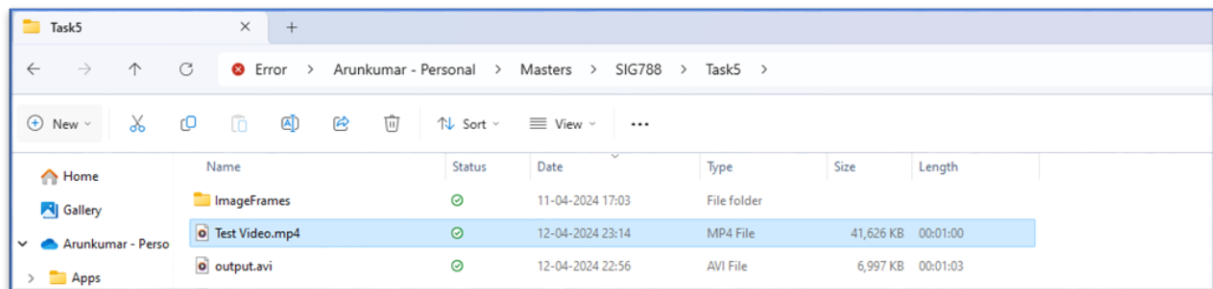
# Extract and predict using one frame per second
for frame in extract_frames(video_file, frame_interval=1.0): # Extract one frame per second
    _, buffer = cv2.imencode('.jpg', frame)
    response = predict_frame(buffer.tobytes(), prediction_url, prediction_key)
    frame_with_predictions = draw_predictions(frame, response, 0.5) # Apply thresholds of 50%
    out.write(frame_with_predictions)

# Release the VideoWriter
out.release()

```

### Output:

The output.avi has been created and saved in the working directory.



### Conclusion:

The project successfully automated for object detection using videos by extracting frames from YouTube videos and predicting using an Azure Custom Vision model.

**Limitations:**

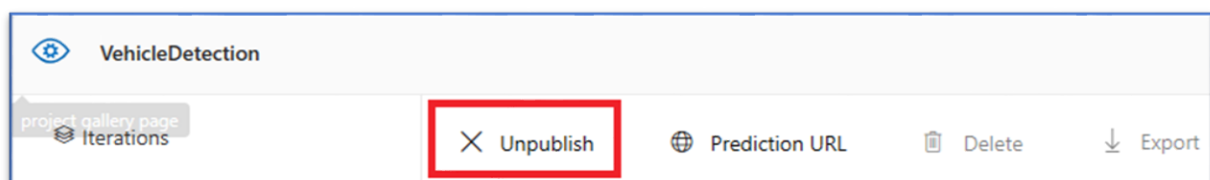
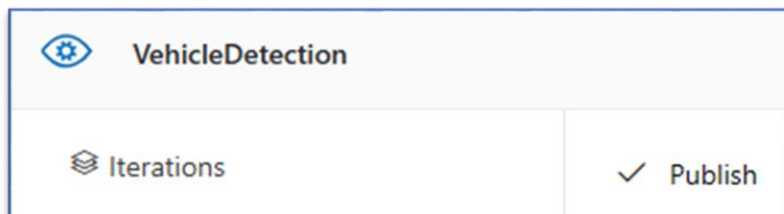
- **Limited Training Data:** The model was trained with only **99 images**, limiting its ability to generalize across varied real-world scenarios.
- **Model Overfitting:** There's a risk of overfitting due to the limited training data.
- **Frame Rate Dependency:** The current setup uses only **one frame per second** will not be adequate for all scenarios.

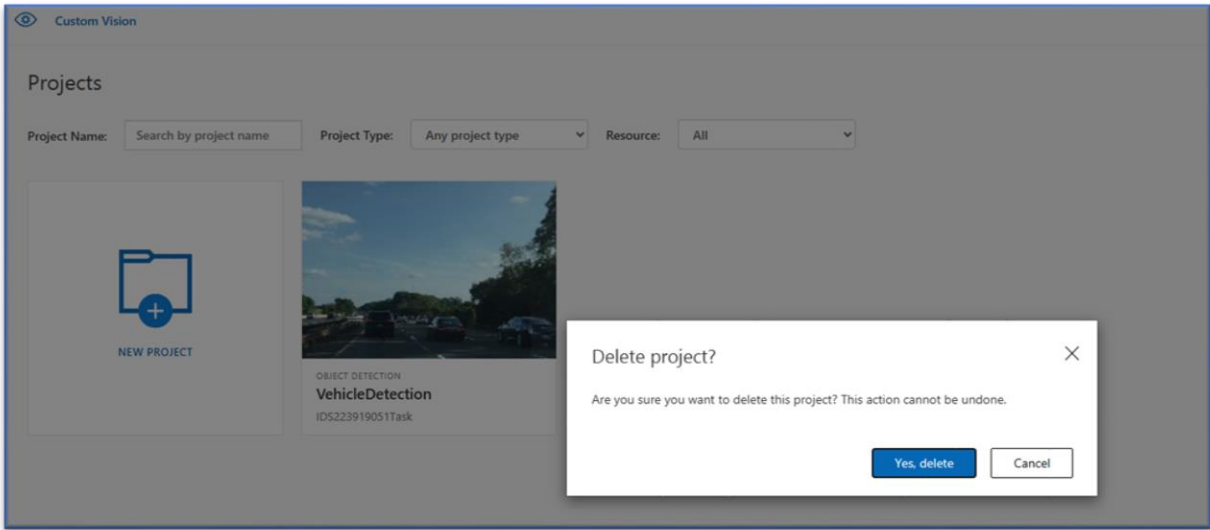
**Next Steps:**

- **Increase Training Data:** Enhance the training dataset with more diverse images to improve model accuracy.
- **Enhance Model Training:** Experiment with different architectures and hyperparameters, and consider data augmentation techniques.
- **Implement Continuous Learning:** Establish a mechanism for continuous learning from new data, including incorrect predictions.
- **Refine Thresholds and Evaluation Metrics:** Adjust the probability threshold and implement additional metrics like F1-score for a comprehensive understanding of the model's performance.

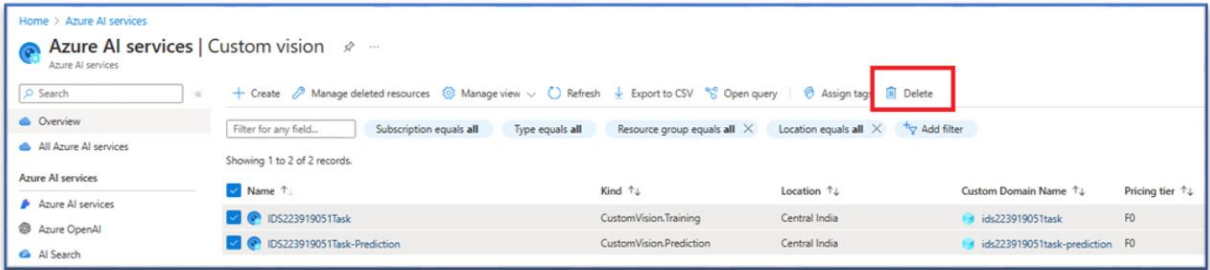
**Clean up Activity:**

As we now completed the project, let's delete the resource and custom vision project.

**Unpublish the Model:****Unpublished:****Deleting the project:**



Deleted the project, now we will get into Azure portal to delete the resources and resources group.



Resources to be deleted (2)

Name	Resource type
IDS223919051Task	CognitiveServicesAccou... <a href="#">Remove</a>
IDS223919051Task-Prediction	CognitiveServicesAccou... <a href="#">Remove</a>

Enter "delete" to confirm deletion \*

Delete

Cancel

Now click on managed deleted resources and purge the deleted resources permanently

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<input checked="" type="checkbox"/>	Name	Deletion date	Scheduled purge date
<input checked="" type="checkbox"/>	IDS223919051Task-Predict...	13/4/2024, 12:55:09 am	15/4/2024, 12:55:09 am
<input checked="" type="checkbox"/>	IDS223919051Task	13/4/2024, 12:55:09 am	15/4/2024, 12:55:09 am

Recover

Purge

Close

Refresh

 Manage deleted resources

Confirm Purge

You won't be able to recover the resources once they are deleted permanently. It could take a few minutes for the operation to complete.

Yes

No

Now click on resource groups and delete resource group

Delete a resource group

The following resource group and all its dependent resources will be permanently deleted.

Resource group to be deleted

RG-S223919051-Task5

Dependent resources to be deleted (0)

All dependent resources, including hidden types, are shown.

Name	Resource type
------	---------------

Enter resource group name to confirm deletion \*

RG-S223919051-Task5










Delete

Cancel

After finishing the work, I have ensured to delete all the resources and resource group to ensure no extra billing for unused resources.



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