

Ans 1(a) $S = \{ (a_1, a_2, a_3, a_4) ; a_1 + a_2 + a_3 + a_4 = 0 \}$
 $T = \{ (a_1, a_2, a_3, a_4) ; a_1 - a_2 + a_3 - a_4 = 0 \}$
 Let $W = S \cap T = \{ (a_1, a_2, a_3, a_4) ; a_1 + a_2 + a_3 + a_4 = 0 ; a_1 - a_2 + a_3 - a_4 = 0 \}$

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 Calculated mistake
 could be avoided

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Now $\begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & -1 & 1 & -1 \end{bmatrix} \begin{bmatrix} a_1 \\ a_2 \\ a_3 \\ a_4 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$

Basis should be set of 2 elements
 set which generates S & T

$R_2 \rightarrow R_2 - R_1 \Rightarrow \begin{bmatrix} 1 & 1 & 1 & 1 \\ 0 & -2 & 0 & -2 \end{bmatrix} \begin{bmatrix} a_1 \\ a_2 \\ a_3 \\ a_4 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$

hence dimension of $W = 4 - 2 = 2$
 and basis = $\{ (1, 0), (1, -2) \}$

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Ans 1(c) $f(x,y) = \begin{cases} \frac{xy}{\sqrt{x^2+y^2}} & (x,y) \neq (0,0) \\ 0 & (x,y) = (0,0) \end{cases}$

let $\epsilon > 0$, then $|f(x,y) - f(0,0)| = \left| \frac{xy}{\sqrt{x^2+y^2}} - 0 \right|$

let $x \rightarrow r \cos \theta$
 $y \rightarrow r \sin \theta$

then $|f(x,y) - f(0,0)| = |r \sin \theta \cos \theta| \leq \left| \frac{r}{2} \right| |\sin 2\theta| \leq \frac{r}{2}$

\therefore if $|f(x,y) - f(0,0)| < \epsilon$ ie $\frac{r}{2} < \epsilon \Rightarrow \sqrt{x^2+y^2} < 2\epsilon$

we have $\delta = 2\epsilon^2$ s.t $|x| < 2\epsilon^2$ and $|y| < 2\epsilon^2$
 $f(x,y)$ is continuous at $(0,0)$

$$\text{Now } f_x(0,0) = \lim_{h \rightarrow 0} \frac{f(h,0) - f(0,0)}{h} = 0$$

$$\text{Similarly } f_y(0,0) = \lim_{k \rightarrow 0} \frac{f(0,k) - f(0,0)}{k} = 0$$

Hence partial derivatives also exist at $(0,0)$

Differentiability at $(0,0)$

Now if it is differentiable at $(0,0)$ following will hold true

$$f(h,k) - f(0,0) = h f_x(0,0) + k f_y(0,0) + h\phi + k\psi$$

where ϕ and ψ are functions which tend to 0

$$\text{as } (x,y) \rightarrow (0,0)$$

$$\text{Now } \frac{hk}{\sqrt{h^2+k^2}} = h\phi + k\psi$$

If $h \rightarrow r \cos \theta$, $k \rightarrow r \sin \theta$, we have

$$r \sin \theta \cos \theta = r \cos \theta \phi + r \sin \theta \psi$$

$$\sin \theta \cos \theta = \cos \theta \phi + \sin \theta \psi$$

Now ϕ and $\psi \rightarrow 0$ as $r \rightarrow 0$

$\therefore \sin \theta \cos \theta = 0$ which is not true for all θ

Hence $f(x,y)$ is not differentiable at $(0,0)$

(9)

(8)

Ans 1(d)

$$\lim_{x \rightarrow 0} \frac{x(1 + a \cos 2x) + b \sin 2x}{x^3} = 1 \quad (3)$$

LHS is $\frac{0}{0}$ hence applying L'Hospital rule

$$\Rightarrow \lim_{x \rightarrow 0} \frac{(1 + a \cos 2x) - 2ax \sin 2x + 2b \cos 2x}{3x^2}$$

It will be $\frac{0}{0}$ form only if $1 + a + 2b = 0$ (1)

Again applying L'Hospital rule we get

$$\Rightarrow \lim_{x \rightarrow 0} \frac{1 - 2a \sin 2x - 2a \sin 2x - 4ax \cos 2x - 2^2 b \sin 2x}{6x}$$

~~It will be $\frac{0}{0}$ form only if~~ It is $\frac{0}{0}$ form

hence again applying same rule

$$\Rightarrow \lim_{x \rightarrow 0} \frac{-8a \cos 2x - 4a \cos 2x + 8ax \sin 2x - 8b \cos 2x}{6}$$

$$= \frac{-8a - 4a - 8b}{6} = 1$$

$$\Rightarrow 12a + 8b + 6 = 0 \quad (2)$$

from (1) and (2) we have

$$12(-2b - 1) + 8b + 6 = 0$$

$$-24b - 12 + 8b + 6 = 0 \Rightarrow -18b = 6$$

and $a = -\frac{1}{3}$ ans

$$-16b = 6 \quad b = \frac{-6}{16} = -\frac{3}{8}$$

$$\Rightarrow b = -\frac{1}{3}$$

Ans 1(e)

Equation of plane containing $\frac{y}{b} + \frac{z}{c} = 1, x=0$ is (4)

$$\frac{y}{b} + \frac{z}{c} - 1 + \lambda x = 0 \quad (1)$$

Symmetric form of line $\frac{x}{a} - \frac{z}{c} = 1, y=0$ is given by

$$\frac{x}{a} = \frac{y}{0} = \frac{z+c}{c} \quad (2) = r_1 \text{ (say)}$$

If (2) is parallel to (1) then

$$\lambda a + \frac{c}{c} = 0 \Rightarrow \lambda = -\frac{1}{a}$$

hence given plane is

$$\boxed{\frac{x}{a} - \frac{y}{b} - \frac{z}{c} + 1 = 0} \quad \underline{\underline{\text{Ans.}}}$$

Now 2d is given shortest distance b/w lines

Symmetrical form of line $\frac{y}{b} + \frac{z}{c} = 1, x=0$ is

$$\frac{x}{0} = \frac{y}{b} = \frac{z-c}{-c} \quad (3) = r_2 \text{ (say)}$$

Any point on line (2) is $(ar_1, 0, cr_1 - c)$

Any point on line (3) is $(0, br_2, -cr_2 + c)$

\therefore Directional ratio of SD is $(ar_1, -br_2, c(r_1 + r_2) - 2c)$

If it is \perp ~~parallel~~ to (2) then

$$a^2 r_1 + c^2 (r_1 + r_2) - 2c^2 = 0 \quad (4)$$

Similarly if it \perp ~~parallel~~ to (3) then

$$-b^2 r_2 - c^2 (r_1 + r_2) + 2c^2 = 0 \quad (5)$$

ans. 2(a)

$$u_1 = (1, -2, 0, 3) \quad u_2 = (2, 3, 0, -1) \quad u_3 = (2, -1, 2, 1) \quad (8)$$

Now $v = (3, 9, -4, -2)$

$$\det (3, 9, -4, -2) = a(1, -2, 0, 3) + b(2, 3, 0, -1) + c(2, -1, 2, 1)$$

$$3 = a + 2b + 3c$$

$$9 = -2a + 3b + 9c$$

$$-4 = -4c$$

$$-2 = 3a - b - 2c$$

$\Rightarrow c = 1$, hence equations become

$$a + 2b = 0$$

$$-2a + 3b = 0$$

$$3a - b = 0$$

which is not true except for $a = b = 0$

ans 2(a)(i) $u_1 = (1, -2, 0, 3) \quad u_2 = (2, 3, 0, -1) \quad u_3 = (2, -1, 2, 1)$

Now $\det v = (3, 9, -4, -2) = a(1, -2, 0, 3) + b(2, 3, 0, -1) + c(2, -1, 2, 1)$

$$\Rightarrow 3 = a + 2b + 2c$$

$$9 = -2a + 3b - c$$

$$-4 = 2c$$

$$-2 = 3a - b + c \quad \checkmark$$

$\Rightarrow \boxed{c = -2}$ hence equations become

$$\Rightarrow a + 2b = 7$$

$$2a - 3b = -7$$

$$\Rightarrow a = 1, b = 3 \quad \checkmark$$

$$3a - b = 0$$

hence v is linear combination of given vectors

Ans

Ans 2(a)(ii)

$$\text{Let } (a, b, c) = p(2, 1, 0) + q(1, -1, 2) + r(0, 3, -4)$$

$$2p + q = a$$

$$p - q + 3r = b$$

$$2q - 4r = c$$

$$\Rightarrow \frac{a-q}{2} - q + 3\left(\frac{2q-c}{4}\right) = b \Rightarrow 2a - 2q - 4q + 6q - 3c = 4b$$

$$\Rightarrow \begin{bmatrix} 1 & -1 & 3 \\ 2 & 1 & 0 \\ 0 & 2 & -4 \end{bmatrix} \begin{bmatrix} p \\ q \\ r \end{bmatrix} = \begin{bmatrix} a \\ b \\ c \end{bmatrix}$$

$$R_2 \rightarrow R_2 - 2R_1 \Rightarrow \begin{bmatrix} 1 & -1 & 3 \\ 0 & 3 & -6 \\ 0 & 2 & -4 \end{bmatrix} \begin{bmatrix} p \\ q \\ r \end{bmatrix} = \begin{bmatrix} a \\ a-2b \\ c \end{bmatrix}$$

$$R_3 \rightarrow \frac{R_3}{2}, R_2 \rightarrow \frac{R_2}{3}, R_3 \rightarrow R_3 - R_2 \text{ we get}$$

$$\begin{bmatrix} 1 & -1 & 3 \\ 0 & 1 & -2 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} p \\ q \\ r \end{bmatrix} = \begin{bmatrix} a \\ \frac{a-2b}{3} \\ \frac{c}{2} - \frac{a}{3} + \frac{2b}{3} \end{bmatrix}$$

Now given system will be consistent only if

$$\frac{c}{2} - \frac{a}{3} + \frac{2b}{3} = 0$$

$$\Rightarrow \boxed{3a - 2a + 4b = 0} \text{ Ans.}$$

$$3c - 2a + 4b = 0$$

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Ans 2(b)

Both matrices will have same column space if their

transpose have row space, hence

$$A^T = \begin{bmatrix} 1 & 1 & 1 \\ 3 & 4 & 1 \\ 5 & 3 & 0 \end{bmatrix}, B^T = \begin{bmatrix} 1 & -2 & 7 \\ 2 & -3 & 12 \\ 3 & -4 & 17 \end{bmatrix}$$

Non need to row por
Directly do column operator

A

$$R_2 \rightarrow R_2 - 3R_1$$

$$R_3 \rightarrow R_3 - 5R_1$$

$$\Rightarrow \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & -2 \\ 0 & -2 & 4 \end{bmatrix}$$

(8)

$$R_3 \rightarrow R_3 + 2R_2$$

$$\Rightarrow \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & -2 \\ 0 & 0 & 0 \end{bmatrix} \quad \text{--- (1)}$$

B

$$R_2 \rightarrow R_2 - 2R_1$$

$$R_3 \rightarrow R_3 - 3R_1$$

$$\Rightarrow \begin{bmatrix} 1 & -2 & 7 \\ 0 & 1 & -2 \\ 0 & 2 & -4 \end{bmatrix}$$

$$R_3 \rightarrow R_3 - 2R_2$$

$$\Rightarrow \begin{bmatrix} 1 & -2 & 7 \\ 0 & 1 & -2 \\ 0 & 0 & 0 \end{bmatrix} \quad \text{--- (2)}$$

Using (1) and applying $R_2 \rightarrow R_2 - R_1$ we get

$$\Rightarrow \begin{bmatrix} 1 & 0 & 3 \\ 0 & 1 & -2 \\ 0 & 0 & 0 \end{bmatrix} \quad \text{--- (3)}$$

Using (2) and apply $R_1 \rightarrow R_1 + 2R_2$ we get

$$\Rightarrow \begin{bmatrix} 1 & 0 & 3 \\ 0 & 1 & -2 \\ 0 & 0 & 0 \end{bmatrix} \quad \text{--- (4)}$$

(6)

Since (3) and (4) are same, hence given matrices have same column space



Ans 2(c)

$$f(x, y, z) = x - 2y + 5z \quad \text{--- (1)}$$

$$\text{Let } g(x, y, z) = x^2 + y^2 + z^2 - 30 \quad \text{--- (2)}$$

Differentiating both equations partially, multiplying (2) then by λ and adding corresponding partial elements coefficients

$$\Rightarrow 1 + 2\lambda x = 0 \quad \Rightarrow x = -1/2\lambda$$

$$-2 + 2\lambda y = 0 \quad \Rightarrow y = 2/2\lambda$$

$$5 + 2\lambda z = 0 \quad \Rightarrow z = -5/2\lambda$$

Using in (2) we get $\frac{1+4+25}{4\lambda^2} = 30 \Rightarrow \lambda = \pm \frac{1}{2}$

hence two possible points are $(-1, 2, -5)$ and $(1, -2, 5)$

Now At

$(-1, 2, -5)$

$$f = -1 - 4 - 25 = -30$$

At $(1, -2, 5)$

$$f = 1 + 4 + 25 = 30$$

Verification

Take y as fixed variable s.t z is only dependent on y .

Diff (1) wrt $x \Rightarrow \frac{\partial f}{\partial x} = 1 + 5 \frac{\partial z}{\partial x} = 0 \quad \text{--- (3)}$

Diff (2) wrt $x \Rightarrow 2x + 2z \frac{\partial z}{\partial x} = 0 \Rightarrow \frac{\partial z}{\partial x} = -\frac{x}{z}$

hence $\frac{\partial f}{\partial x} = 1 - \frac{5x}{z}$, Again diff wrt x

$$\Rightarrow \frac{\partial^2 f}{\partial x^2} = -\frac{5}{z} + \frac{5x}{z^2} \frac{\partial z}{\partial x} = -\frac{5}{z} - \frac{5x^2}{z^3}$$

Now $\frac{\partial^2 f}{\partial x^2}$ at $(-1, 2, -5) > 0$, hence -30 is minimum at $(-1, 2, -5)$
and $\frac{\partial^2 f}{\partial x^2}$ at $(1, -2, 5) < 0$ hence 30 is max at $(1, -2, 5)$

Ans 3(a)

$$T(x, y, z) = (x+y+z, x+2y-3z, 2x+3y-2z, 3x+4y-z)$$

Kernel is given by $x+y+z=0$, $2x+3y-2z=0$
 $x+2y-3z=0$, $3x+4y-z=0$

Take
$$\begin{bmatrix} 1 & 1 & 1 \\ 2 & 3 & -2 \\ 1 & 2 & -3 \\ 3 & 4 & -1 \end{bmatrix}$$

$R_2 \rightarrow R_2 - 2R_1$, $R_3 \rightarrow R_3 - R_1$, $R_4 \rightarrow R_4 - 3R_1 \Rightarrow \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & -4 \\ 0 & 1 & -4 \\ 0 & 1 & -4 \end{bmatrix}$

$R_3 \rightarrow R_3 - R_2$, $R_4 \rightarrow R_4 - R_2 \Rightarrow \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & -4 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$

Hence Nullity = $\boxed{3-2=1}$ and Basis for kernel is given by

$$x+y+z=0$$

$$y-4z=0 \Rightarrow x=-5z, y=4z, z$$

ie $\boxed{\text{Kernel} = \{(-5, 4, 1)\}}$

Now Rank + Nullity = Dim R^3

ie Rank + 1 = 3 $\Rightarrow \boxed{\text{Rank} = 2}$

Range

$$T(x, y, z) = x(1, 1, 2, 3) + y(1, 2, 3, 4) + z(1, -3, -2, -1)$$

Take
$$\begin{bmatrix} 1 & 1 & 2 & 3 \\ 1 & 2 & 3 & 4 \\ 1 & -3 & -2 & -1 \end{bmatrix}$$
, $R_2 \rightarrow R_2 - R_1$
 $R_3 \rightarrow R_3 - R_1 \Rightarrow \begin{bmatrix} 1 & 1 & 2 & 3 \\ 0 & 1 & 1 & 1 \\ 0 & -4 & -4 & -4 \end{bmatrix}$

$R_3 \rightarrow R_3 + 4R_2 \Rightarrow \begin{bmatrix} 1 & 1 & 2 & 3 \\ 0 & 1 & 1 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix}$

hence $\boxed{\text{Range} = \{(1, 1, 2, 3), (0, 1, 1, 1)\}}$

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Ans-3(b) (i)

Let A be non singular, hence A^{-1} exists. s.t. (9)

$$AA^{-1} = I \Rightarrow |AA^{-1}| = 1 \Rightarrow |A||A^{-1}| = 1$$

hence $|A^{-1}| = |A|^{-1}$ hence proved.

Ans 3(b) (ii)

$$\text{Take } C = B^T A B$$

$$\Rightarrow |C| = |B^T A B| = |B^T| |A| |B| = |B^T| |B| |A|$$

$$= |B^T B| |A| = |A|$$

hence $B^T A B$ and A have same determinant

Ans 3 (E)

$$f(x,y) = \begin{cases} (x^2+y^2) \log(x^2+y^2) & (x,y) \neq (0,0) \\ 0 & (x,y) = (0,0) \end{cases}$$

Now $f_{xy}(0,0) = \lim_{k \rightarrow 0} \frac{f_x(0,k) - f_x(0,0)}{k}$

where $f_x(0,k) = \lim_{h \rightarrow 0} \frac{f(h,k) - f(0,k)}{h} = \frac{(h^2+k^2) \log(h^2+k^2) - k^2 \log k^2}{h}$

$$= \lim_{h \rightarrow 0} \frac{h \log(h^2+k^2) + k^2 \log \frac{(h^2+k^2)}{k^2}}{h} \quad \left(\frac{0}{0}\right) \text{ form}$$

$$= \lim_{h \rightarrow 0} k^2 \cdot \left[\frac{2h}{h^2+k^2} \right] = 0$$

Similarly $f_x(0,0) = \lim_{h \rightarrow 0} \frac{f(h,0) - f(0,0)}{h} = \frac{h^2 \log h^2}{h} = 0$

hence $f_{xy}(0,0) = 0$ and similarly $f_{yx}(0,0) = 0$

ie $f_{xy}(0,0) = f_{yx}(0,0) = 0$

Differentiating given fn wrt x we get

$$f_x = 2x \log(x^2+y^2) + \frac{(x^2+y^2)}{x^2+y^2} \cdot 2x$$

$$= 2x(1 + \log(x^2+y^2)) \quad \textcircled{1}$$

Now differentiating (1) wrt y

$$f_{xy} = \frac{2x}{x^2+y^2} \cdot 2y = \frac{4xy}{x^2+y^2}$$

let $y \rightarrow mx$ s.t. $y \rightarrow 0, x \rightarrow 0$

$$\text{hence } f_{xy} = \frac{4 \cdot x \cdot mx}{x^2 + m^2 x^2} = \frac{4m}{1+m^2}$$

which is different for different paths, hence

$f_{xy}(0,0) \neq 0$ for all paths, hence f_{xy} is not continuous at $(0,0)$
Similarly f_{yx} is not continuous at $(0,0)$

Ans 3(d)

Locus of line of intersection of perpendicular
tangent planes to $ax^2 + by^2 + cz^2 = 0$

Ans 5(a) $16(x+1)^4 y_4 + 96(x+1)^3 y_3 + 104(x+1)^2 y_2 + 8(x+1) y_1 + y = x^2 + 4x^3$ (11)

Let $x+1 = e^z \Rightarrow \log(x+1) = z \Rightarrow \frac{1}{x+1} \cdot \frac{dx}{dy} = \frac{dz}{dy}$ ✓

$\Rightarrow D_1 \equiv \frac{d}{dz} = (x+1) \frac{d}{dx}$

hence equation becomes -

$(6 D_1(D_1+1)(D_1+2)(D_1+3) + 96 D_1(D_1+1)(D_1+2) + 104 D_1(D_1+2) + 8 D_1 + 1) =$
 $= e^z(e^z + 2) = e^{2z} + 2e^z$

Complementary Solution

$16(D_1^2 - D_1)(D_1^2 - 5D_1 + 6) + 96 D_1(D_1^2 - 3D_1 + 2) + 104 D_1^2 - 8 D_1 + 8 D_1 + 1 = 0$ ✓

$\Rightarrow (4D_1^2 - 1)^2 = 0 \Rightarrow D_1 = \pm \frac{1}{2}$ twice

hence Complementary function is $y = (C_1 + z C_2) e^{z/2} + (C_3 + z C_4) e^{-z/2}$

Particular Integral

$\Rightarrow \frac{e^{2z} + 2e^z}{(4D_1^2 - 1)^2} = \frac{e^{2z}}{(4 \cdot \frac{1}{4} - 1)^2} + \frac{2e^z}{(4 \cdot \frac{1}{4} - 1)^2}$

$= \frac{e^{2z}}{2 \cdot 25} + \frac{2e^z}{9}$ ✓

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hence solution is $y = (C_1 + \log(x+1) C_2) \log \sqrt{x+1} + (C_3 + \log(x+1) C_4) \log \frac{1}{\sqrt{x+1}}$
 $+ \frac{\log(x+1)^2}{2 \cdot 25} + \frac{1}{9} + \frac{(x+1)^2}{2 \cdot 25} + \frac{2(x+1)}{9}$

Ans

Ans 5(b)

$$r = \frac{2a}{1 + \cos \theta} \Rightarrow \log r = \log 2a - \log(1 + \cos \theta)$$

diff w.r.t $\theta \Rightarrow \frac{1}{r} \frac{dr}{d\theta} = \frac{\sin \theta}{1 + \cos \theta} \Rightarrow \frac{1}{r} \frac{dr}{d\theta} = \frac{2 \sin \theta/2 \cos \theta/2}{2 \cos^2 \theta/2}$

replacing $\frac{d\theta}{dr} \rightarrow \frac{-1}{r^2} \frac{dr}{d\theta}$, hence eqn. become

$$\frac{1}{r} \left(-r^2 \frac{d\theta}{dr} \right) = \tan \theta/2 \Rightarrow \frac{d\theta}{\tan \theta/2} + \frac{dr}{r} = 0$$

$\Rightarrow 2 \log \sin \theta/2 + \log r = \log C$ where C is constant

$$\sin^2 \theta/2 \cdot r = C \Rightarrow \boxed{r = C \operatorname{cosec}^2 \theta/2}$$

Ans 5(c)

Let OB be given rod of length $2a$ with centre at h . Let AB be peg s.t. $AB = b$

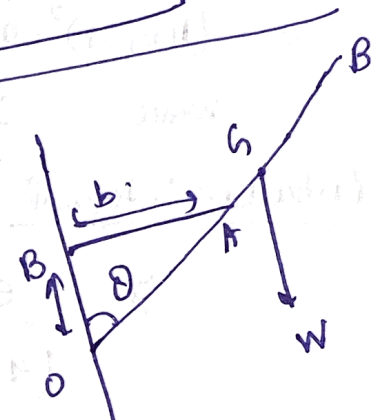
Now x be distance of h from A

$$x = a \cos \theta - b \cot \theta$$

$$\Rightarrow \frac{dx}{d\theta} = -a \sin \theta + b \operatorname{cosec}^2 \theta$$

for position $\frac{dx}{d\theta} = 0 \Rightarrow \boxed{\sin^3 \theta = b/a}$

Now $\frac{d^2x}{d\theta^2} = -a \cos \theta - 2b \operatorname{cosec}^2 \theta \cot \theta < 0$
 \Rightarrow Hence System is in equilibrium stable.



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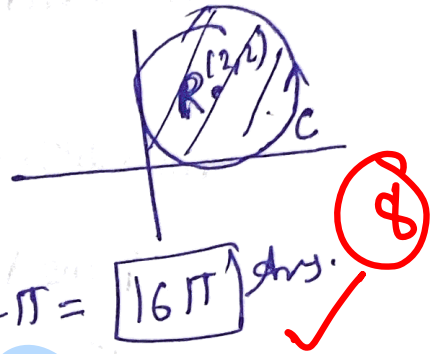
Ans 5(e)

$$f(x,y) = \int_C (4x-2y) dx + (2x-4y) dy$$

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Now according to Green's theorem

$$\int_C (4x-2y) dx + (2x-4y) dy = \iint_R (Q_x - P_y) dx dy$$



$$= \iint_R 4 dx dy = 4 \cdot 4\pi = 16\pi \text{ Ans.}$$

Ans 6(a)

$$x^2 + y^2 + 2gx + c = 0 \quad \text{--- (1)}$$

diff w.r.t x

$$2x + 2y \frac{dy}{dx} + 2g = 0 \Rightarrow g = -(x + y^2)$$

using in (1) we get $x^2 + y^2 - 2x(x + y^2) + c = 0$

Replacing y by $-\frac{1}{y}$ we get

$$x^2 + y^2 - 2x\left(x - \frac{1}{y}\right) + c = 0 \Rightarrow y^2 - x^2 + \frac{2xy}{y} + c = 0$$

$$\frac{y^2 - x^2 + y + \frac{2xy}{y} + c = 0}{y} \Rightarrow \underbrace{dy \left(\frac{y^2 - x^2 + c}{y} \right)}_N + \underbrace{\frac{2xy dx}{y}}_M = 0$$

$\frac{dy}{dx}$ Now $\frac{1}{N} \left(\frac{\partial N}{\partial x} - \frac{\partial M}{\partial y} \right)$ is integrable

ie $e^{\int \frac{1}{2xy} (-2x - 2x)} = e^{\int -\frac{2}{y} dy} = \frac{1}{y^2}$ is integrable.

hence exact eq. is $dy \left(1 - \frac{x^2}{y^2} + \frac{c}{y^2} \right) + dx \cdot \frac{2x}{y} = 0$

Solution is

$$\boxed{\frac{x^2}{y} + y - \frac{c}{y} = C_1}$$

✓ 13

Ans (b)

Let AOB be heavy chain of length $2l$

$$\text{Then } \tan \lambda = \frac{R}{\mu R} = \frac{1}{\mu}$$

Now let tension at B be T_B

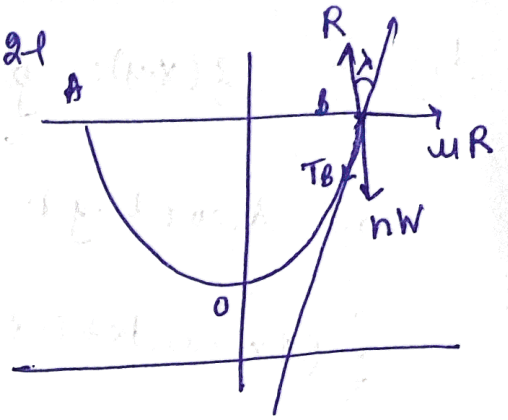
$$T_B \cos \lambda + nW = R$$

$$T_B \sin \lambda = \mu R$$

$$\text{Also } T_B \sin \lambda = nW \quad \text{and } T_B \cos \lambda = \frac{W \cdot y_B}{2l}$$

$$\text{hence } \frac{W y_B}{2l} + nW = R$$

$$nW = \mu R$$



Ans-6(c)

Case I

Let actual velocity of wind be $x\hat{i} + y\hat{j}$

When person moving westwards, his velocity is $4\hat{i}$
Resultant is blowing from north, hence $x = -4$

$$\therefore \text{wind velocity} = -4\hat{i} + y\hat{j}$$

Case II

When person moving twice velocity i.e. his velocity is $8\hat{i}$
Resultant is $4\hat{i} + y\hat{j}$ which is north east, hence

$$y = -4$$

$$\therefore \text{wind velocity} = -4\hat{i} - 4\hat{j}$$

Ans-6(c)ii

$$\phi = xy^2 + yz^3$$

$$\nabla\phi = y^2\hat{i} + (2xy + z^3)\hat{j} + 3yz^2\hat{k} \quad (1)$$

Normal to surface $x \log z - y^2 = -4$ is

$$\log z\hat{i} - 2y\hat{j} + \frac{x}{z}\hat{k} \Big|_{(-1, 2, 1)} = 0\hat{i} - 4\hat{j} - \hat{k} \quad (2)$$

Component of (1) in direction of (2) is given by.

$$\frac{-4(2xy + z^3) - 3yz^2}{\sqrt{17}} \Big|_{(2, -1, 1)} = \frac{-4(2 \cdot 2 \cdot (-1) + 1) - 3 \cdot (-1) \cdot 1}{\sqrt{17}}$$
$$= \frac{-4(-3) + 3}{\sqrt{17}} = \frac{15}{\sqrt{17}}$$

(b) ✓

Ans 1 (b) (i)

$$\text{Let } A = \begin{bmatrix} 1 & 2 & 0 \\ 0 & 2 & 4 \\ 0 & 0 & 3 \end{bmatrix}$$

(15)

$$\text{adj}A = \begin{bmatrix} 6 & -6 & +8 \\ 0 & 3 & -4 \\ 0 & 0 & 2 \end{bmatrix} \text{ and } |A| = 8$$

↪ Given to 25⁶

$$\text{hence Inverse of } A = \frac{1}{8} \begin{bmatrix} 6 & -6 & 8 \\ 0 & 3 & -4 \\ 0 & 0 & 2 \end{bmatrix}$$

$$\text{Inverse of } A \text{ in } \mathbb{Z}_5 = \frac{1}{8} \begin{bmatrix} 1 & -1 & 3 \\ 0 & 3 & -4 \\ 0 & 0 & 2 \end{bmatrix} \text{ Ans.}$$

SuccessClap