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CONTENT FOR JUDGED AWARDS

THINK: 6, 7, 8, 11

CONNECT: 1, 3, 4, 5, 12, 13, 14

INNOVATE: 8
DESIGN: 11
CONTROL: 9, 10

MOTIVATE: 3, 4, 12, 13, 14

TEAM DESCRIPTION

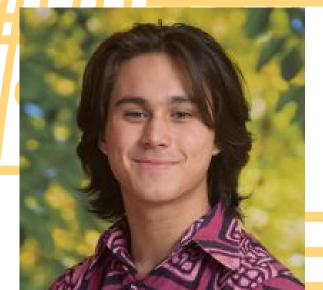
WE ARE TEAM 252, ELECTRIC QUAHOGS,
AN FTC TEAM COMPETING OUT OF THE
WHEELER SCHOOL IN PROVIDENCE, RHODE
ISLAND. WE'VE BEEN PARTICIPATING IN
FTC FOR 15 YEARS!

SUSTAINABILITY PLAN

WE HAVE LAUNCHED A NEW PRE-SEASON TRAINING PROGRAM IN WHICH RETURNING MEMBERS BRUSHED UP ON OLDER SKILLS AND NEWER MEMBERS GET AN EARLY START ON LEARNING WHAT FIRST PARTICIPATION LOOKS LIKE. BECAUSE OF OUR RECRUITING EFFORTS AND SUCCESS IN COMPETITION LAST YEAR, WE MANAGED TO DOUBLE THE SIZE OF OUR SCHOOL'S ROBOTICS PROGRAM FROM 10 MEMBERS TO 22 THIS YEAR. THIS MEANS THAT WE NOW HAVE PEOPLE DEDICATED TO FUNDRAISING AND OUTREACH; GAINING US 2 NEW SPONSORS AND PROVIDING FOCUS TO SOLIDIFY OUR FINANCIAL SYSTEM.

ON TOP OF ALL OF OUR INTERNAL GROWTH WE HAVE MADE AN EFFORT TO CREATE AND MAINTAIN LASTING RELATIONSHIPS WITH OTHER TEAMS IN OUR COMMUNITY SUCH AS TEAM 16008 THE ARMORED ARTEMIS'S, AND TEAM 22686 THE BLACKSTONE ACADEMY BULLDOGS.

OUR TEAM



MYLES JOHNSON, CO-CAPTAIN '23 HE/HIM



MAYTE SEGURA, CO-CAPTAIN '24 SHE/HER



BEATRICE SCHROEDER, '24
SHE /HER



LILY THORNTON, '24 XE/HE/SHE



DANIEL DUARTE-BAIRD, '25
HE/HIM



GRIFFIN HAISMAN, '25, HE/HIM



CHARLIE SHEA, '25, HE/HIM



LUYAO LEI, '26 SHE/HER



SABRINA ANDREU GONZALEZ, '26, SHE/HER

COACH & MENTORS

NAPALI RAYMUNDO

PROGRAMMING/MECHANICS MENTOR FTC ALUM, #4174

ZOE RUDOLPH-LARREA

OPERATIONS MENTOR FTC ALUM, #252

SOPHIE GINSBERG-HAYES

MECHANICS MENTOR FTC ALUM, #2856 & 8032

DYLAN RYDER

COACH
WHEELER SCHOOL DIB LAB DIRECTOR

REBECCA WOLKOFF

PROGRAMMING MENTOR FRC #695

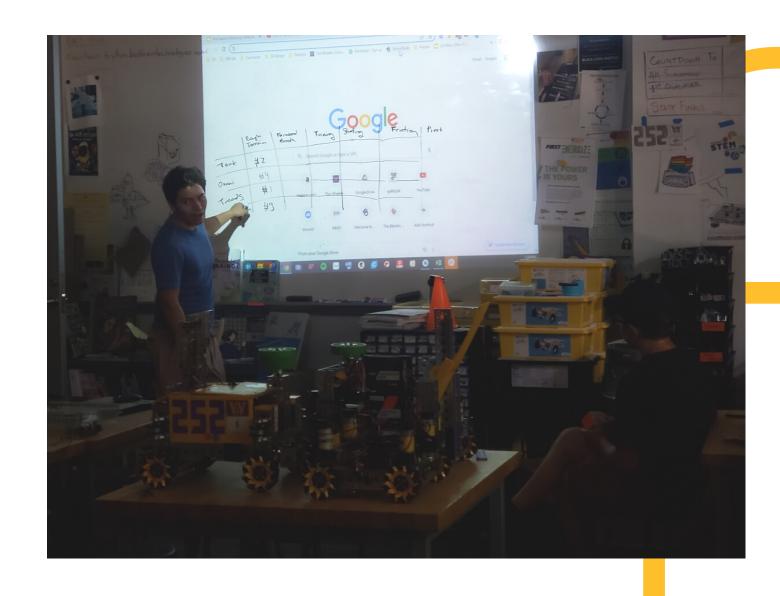
TEAM DETAILS

AS MENTIONED BEFORE, THIS YEAR WE LAUNCHED OUR PRESEASON PROGRAM! NEW AND RETURNING MEMBERS SPENDING TIME TOGETHER BEFORE THE SEASON STARTED, ESTABLISHED A LEARNING FRIENDLY ENVIRONMENT WHERE VETERANS WERE ABLE TO HELP TEACH NEWER MEMBERS IMPORTANT SKILLS FOR THE UPCOMING SEASON LIKE: PROGRAMMING, BUILDING, CAD, FUNDRAISING, AND OPERATIONS. THIS GAVE NEWER MEMBERS A HEAD START ON THINGS THEY WOULD HAVE OTHERWISE HAD TO LEARN DURING THE SEASON.

BY INTRODUCING THESE SKILLS EARLIER, MEMBERS WERE ABLE TO LEARN FASTER. WE ALSO FOCUSED ON MIDDLE SCHOOL CENTERED OUTREACH WITHIN OUR SCHOOL, ALLOWING 18 SEVENTH AND EIGHTH GRADERS THAT REGULARLY ATTENDED OUR WORKSHOPS AND OPEN HOUSES LAST YEAR ADMISSION FOR PRE-SEASON. IT WAS SO SUCCESSFUL A SECOND TEAM WAS CREATED - 636 OCCAM'S RAZOR CLAMS.

PRE-SEASON SCHEDULE

Monday	Tuesday	Wednesday	Thursday	Friday
8/29	8/30	8/31	9/1	9/2
9AM – 11:30PM:	9AM – 11:30PM:	9AM – 11:30PM:	9AM – 11:30PM:	9am - 11:30PM: CAD
Programing Pt. 1	Programing Pt. 2	Building Pt. 3	Building Pt. 4	Pt. 2
12:30PM – 3PM:	12:30PM – 3PM:	12:30PM – 3PM:	12:30Pm – 3PM:	12:30PM – 3PM:
Building Pt. 1	Building Pt. 2	Programing Pt. 3	CAD Pt. 1	Programing Pt. 4





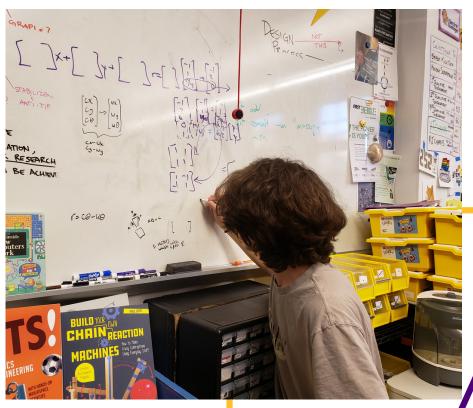
TEAM DETAILS'

OUR PRACTICES ARE A MIXTURE OF IN-SCHOOL TIME AS WELL AS OUT-OF-SCHOOL TIME.

ON TUESDAYS DURING THE SCHOOL DAY, WE HAVE AN "ENRICHMENT" PERIOD. DUE TO TIME RESTRAINTS DURING THIS PERIOD, WE FOCUS ON BETTERING OUR OVERALL OPERATIONS WORK. MONDAY, WEDNESDAY AND FRIDAY ARE AFTER SCHOOL DAYS THAT MEMBERS CAN COME IN ON.

THIS UNIQUE MIX OF AFTER SCHOOL AND IN-SCHOOL MEETINGS ALLOW TEAM MEMBERS TO BETTER DEVOTE WHAT TIME THEY HAVE TO THE TEAM.







TEAM 636 OCCAM'S RAZOR CLAMS IS A TEAM OF ROOKIES THAT WE STARTED THIS YEAR; LARGELY COMPRISED OF NINTH GRADERS AND MIDDLE SCHOOLERS, WITH A FEW 11TH GRADERS. NEAR THE BEGINNING OF THE SEASON IT WAS APPARENT THAT INTEREST LARGELY OUTWEIGHED AVAILABLE SPACE ON OUR TEAM. 252 LEADERSHIP SAT DOWN AND MADE THE DIFFICULT DECISION OF WHICH 2 NEW RECRUITS WE WOULD GRACIOUSLY INVITE TO OUR TEAM. WHEN MAKING OUR DECISION WE MADE AN ACTIVE EFFORT TO ENSURE ENOUGH DIVERSITY IN INTEREST AND SKILL LEVEL AMONG THE TEAM TO PROVIDE A SOLID FOUNDATION FOR SUCCESS. WE SHARE OUR PRACTICE TIME WITH THEM AND HAVE MADE AN ACTIVE EFFORT TO PROVIDE THEM WITH ALL OF THE SUPPORT THEY NEED, FROM CODING ADVICE TO TEAM MANAGEMENT TIPS.



BUDGETING & FUNDRAISING

THIS YEAR WE HAVE FOCUSED MORE ON FUNDRAISING AND BUDGETING THAN PREVIOUS YEARS. ONE OF OUR GOALS GOING INTO THIS SEASON WAS TO CREATE A BETTER FINANCIAL SYSTEM. TO ACHIEVE THIS WE CREATED A SPREADSHEET WHERE WE KEEP TRACK OF OUR EXPENSES AND INCOME TO HAVE A BETTER UNDERSTANDING OF OUR FINANCIAL STATUS.

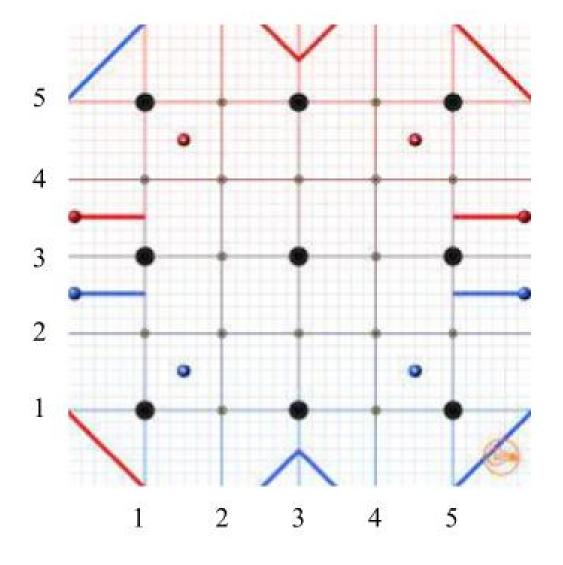
	<u>/////////////////////////////////////</u>	<u>////X//</u>		//////////
	Grant / Donor Name	Amount	Date	Notes / Follow Up
	(example) Wheeler School	\$1,000.00	9/1/2022	
	Dave's Market	\$250.00	11/28/2022	
	Providence Engineering Society	\$500.00	12/5/2022	
Y				
	Total Grants & Donations	\$1,750.00		
	Total Income	\$1,750.00		
	In-Kind Services	Amount	Date	Notes / Follow Up
	GT3 Creative Inc.	\$200.00		Free vinyl banner

Expenses				
Item	Vendor	Cost	Date Paid	Notes
FIRST Registration	FIRST Inc.	\$295.00		
PowerPlay Game Set	AndyMark	\$252.36		\$450 Full / \$290 Half +54.72
Robotic Parts Kit	GoBilda	\$1,072.00		\$599 FTC Starter Kit \$375 Straffer Kit \$98 Linear Slide Kit
Electronics/Control Set	REV Robotics	\$695.00		
Team Apparel		\$240.00		\$240 ex: ~12 T-Shirts
Team Buttons		\$222 (+ discount?)		for 1,000 buttons (should we add like Honey or Groupon for these things?)
Team Stickers				\$372 ex: 1000 3"x3" Die Cut Stickers
<u>Team Buttons</u>		\$250.00		for 1000 1in buttons
Qualifer Registration Fee	RI-FIRST	\$135.00		\$135 due: Dec
State Final Registration Fee	RI-FIRST	\$230.00		\$230 due: Jan
Total Expenses		\$3,169.36		

WE HAVE GROWN OUR NETWORKING WITH POTENTIAL SPONSORS, AND THROUGH THIS WORK, WE HAVE GAINED TWO NEW DONORS: DAVE'S MARKETPLACE AND THE PROVIDENCE ENGINEERING SOCIETY--WHO HAVE DONATED A TOTAL OF \$750 to our team. We also received an in-kind gift from GT3 Creative Inc. of a vinyl banner, which we plan to utilize at every official competition we attend for years to come.



GAME STRATEGY



- CREATE A VERSATILE ROBOT THAT COULD REACH ALL THREE JUNCTIONS AND BE A STRONG ALLIANCE PARTNER.
- PRIORITIZE DRIVER PRACTICE TO MAXIMIZE CYCLE TIME WITH THE ARM AND CLAW
- CREATE A GRID SYSTEM TO DIFFERENTIATE BETWEEN THE DIFFERENT JUNCTIONS TO MINIMIZE DRIVER-COACH MISCOMMUNICATION DURING MATCHES (SEE PICTURE ABOVE)
- WATCH HIGH-SCORING MATCHES ON YOUTUBE TO RESEARCH AND DEVELOP
 OUR OWN GAME STRATEGIES

DESIGN PROCESS

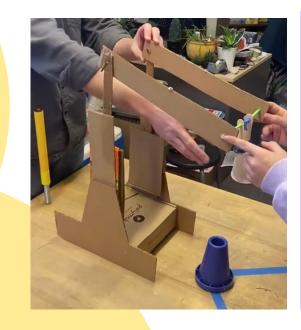
1 - Brainstorming

WE IDENTIFY A GOAL WE WANT OUR ROBOT TO ACHIEVE, THEN BRAINSTORM WHILE SIMULTANEOUSLY RESEARCHING AND EVALUATING MECHANISMS FOR THEIR EFFECTIVENESS AND EFFICIENCY FOR COMPLETING THE TASK.

2- PROTOTYPING

CONCEPTS ARE THEN QUICKLY
PORTOTYPED WITH MATERIALS
LIKE CARDBOARD

CASE STUDY: ROBOT 1'S SIDE PLATES



AFTER BRAINSTORMING THE IDEA FOR THE ROBOT, WE PHYSICALLY PROTOTYPED THE ROBOT 1 WITH CARDBOARD, IT SERVED AS A MODEL WHEN WE STARTED TO CAD.

5 - TESTING

EFFECTIVENESS OF THE MECHANISM IS TESTED AND RECORD TO SEE HOW EFFICIENT IT IS.

3 - CAD/DESIGN

THEN THEY ARE DIGITALLY FABRICATED WITH CAD USING INFORMATION GATHERED FROM RESEARCH AND THE ORIGINAL PROTOTYPE.

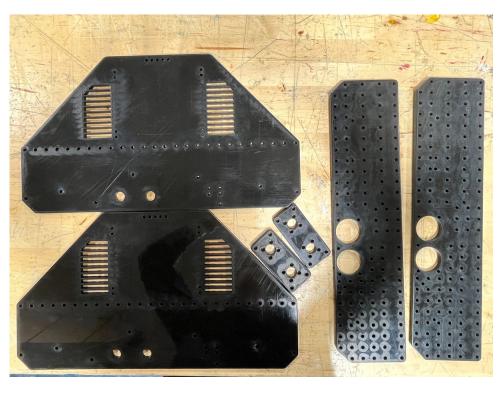


4 -BUILDING

MECHANISMS ARE THEN
ASSEMBLED USING THE CAD MODEL
AS A REFERENCE.

AFTER RESEARCHING OTHER TEAMS SIDE PLATES WE DIGITALLY FABRICATED A CUSTOM DESIGN IN ONSHAPE.

"DESIGNING THE SIDE PLATES FOR LENNY WAS AN INTERESTING PROCESS WITH A LOT OF NEW THINGS TO LEARN. I HAD TO LEARN HOW TO MAKE CUSTOM PARTS USING ONSHAPE, WHICH INCLUDED KNOWING ALL OF THE PARAMETERS WE WOULD NEED TO ACCOUNT FOR." - CHARLIE



WE THEN LASER CUT OUR SIDE PLATES OUT OF DELRIN PLASTIC AND ASSEMBLED OUR ROBOT BASED ON THE CAD.

ROBOT OO OVERVIEW
"FRANT"

1 - H-SHAPED CHASSIS
2 - BELT DRIVEN MECANUM WHEELS
3 - CLAW ON LINEAR SLIDE
4 - 3D PRINTED DOOMETRY WHEELS

AFTER QUALIFIERS, WE RECOGNIZED THAT ROBOT OO DID NOT DISPLAY OUR BEST WORK. NOT MUCH THOUGHT WAS PUT INTO THE DESIGN OR THE PARTS USED. THIS LACK OF CAREFUL PLANNING RESULTED IN AN AWKWARD LAYOUT MAKING DRIVING DIFFICULT. IN ORDER TO FIX THIS, OUR TEAM DECIDED TO CREATE A BRAND-NEW DESIGN IN THE SPAN OF 6 WEEKS. FOR ROBOT O1, WE WANTED TO CUT DOWN OUR CYCLE TIME BY BUILDING A THROUGH-BOT AND IMPROVE OUR CAD SKILLS BY LEARNING HOW TO CREATE CUSTOM SIDE PLATES.

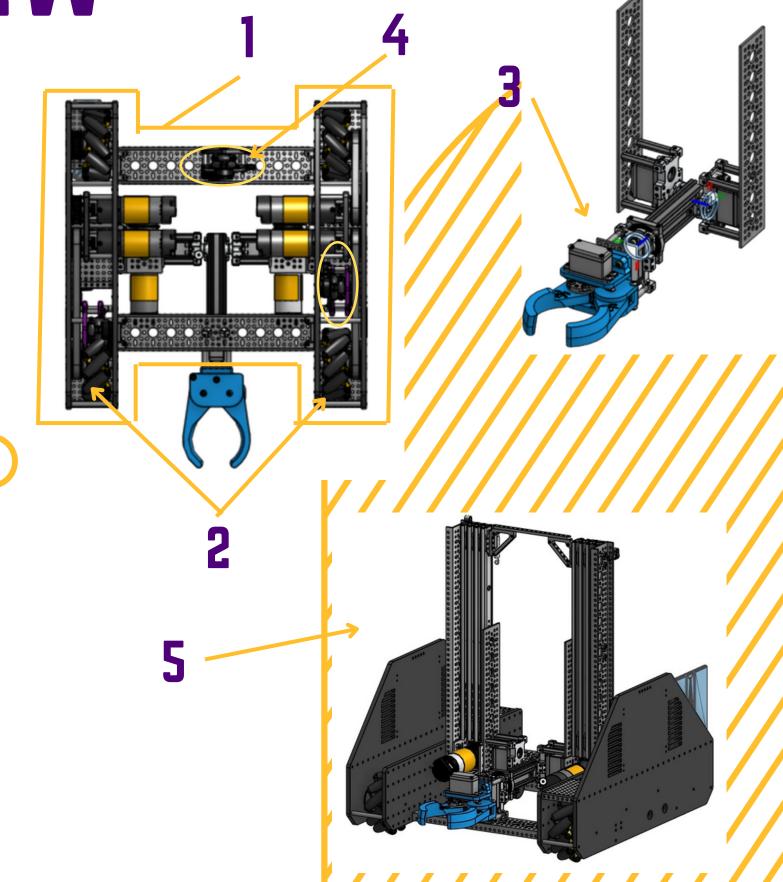
ROBOT 01 OVERVIEW

"LENNY"

- 1 CUSTOM CHASSIS
- 2 BELT DRIVEN MECANUM WHEELS
- 3 ARM AND WRIST CLAW
 - -CENTERED BETWEEN LINEAR SLIDES,

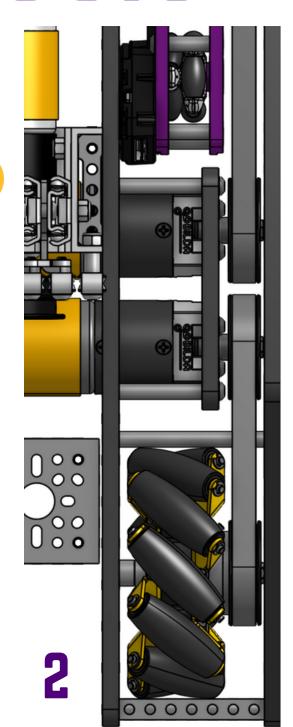
INCREASING STABILITY

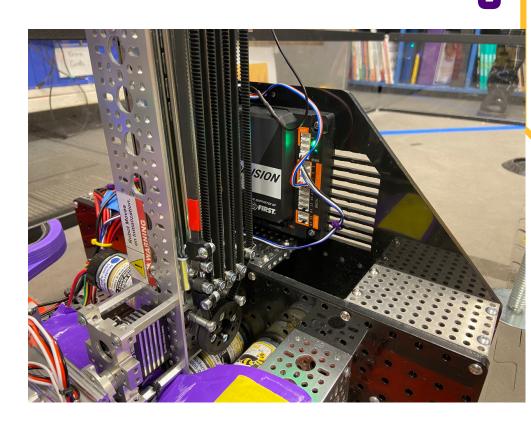
- 4 3D PRINTED ODOMETRY WHEELS
- 5 CUSTOM LASER-CUT CHASSIS PLATES
 - -HOUSES CONTROL HUBS
 - -SHOWS SPONSORS + TEAM NUMBER



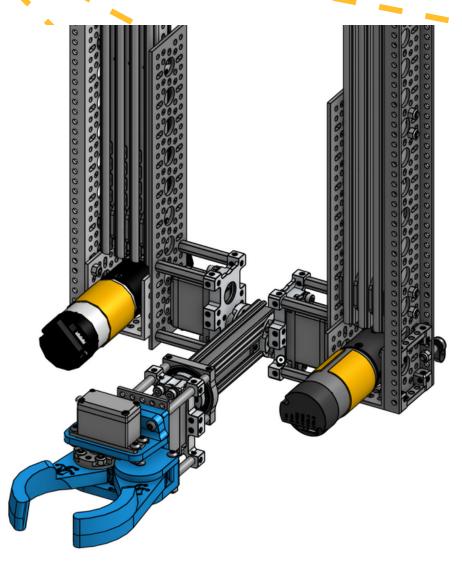
CHASSIS

- (1) CUSTOM DELRIN CHASSIS
 PLATES ARE DURABLE AND RIGID
- TWO CHASSIS PODS
 - (2) CONTAIN WHEELS, MOTORS,BELTS, AND PULLEYS
 - (3) CONTROL + EXPANSIONHUBS
- 1) MOTORS SUNKEN IN SIDE PLATES, SAVE SPACE
- MECANUM WHEELS WITH BELT
 DRIVE



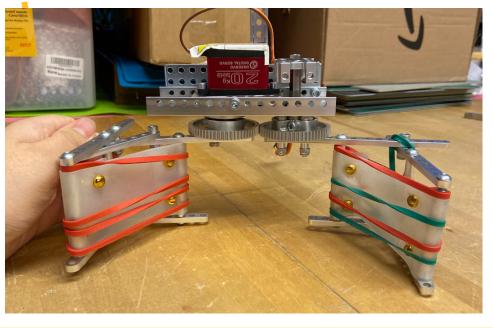




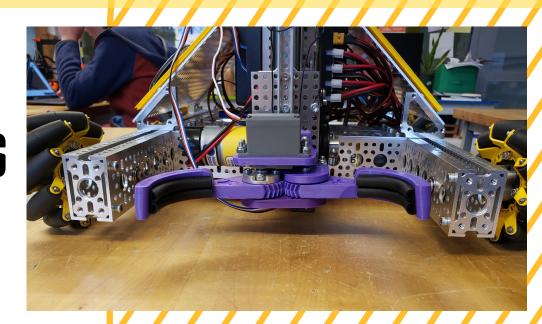


INTAKE

- THROUGH DESIGN ARM FLIPS THROUGH WHILE INSIDE OF THE ROBOT TO REACH OTHER SIDE
 - TWO SYNCED SERVOS ON EITHER SIDE OF ARM
- WRIST FLIPS 180 DEGREES TO SET CONE UPRIGHT ON EITHER SIDE
 - ONE SERVO TO FLIP WRIST; ONE TO OPEN/ CLOSE CLAW
- BELT-DRIVEN LINEAR SLIDES THAT DO NOT REQUIRE CONSTANT TENSIONING; CAN REACH ALL THREE JUNCTION HEIGHTS



TWO ITERATIONS



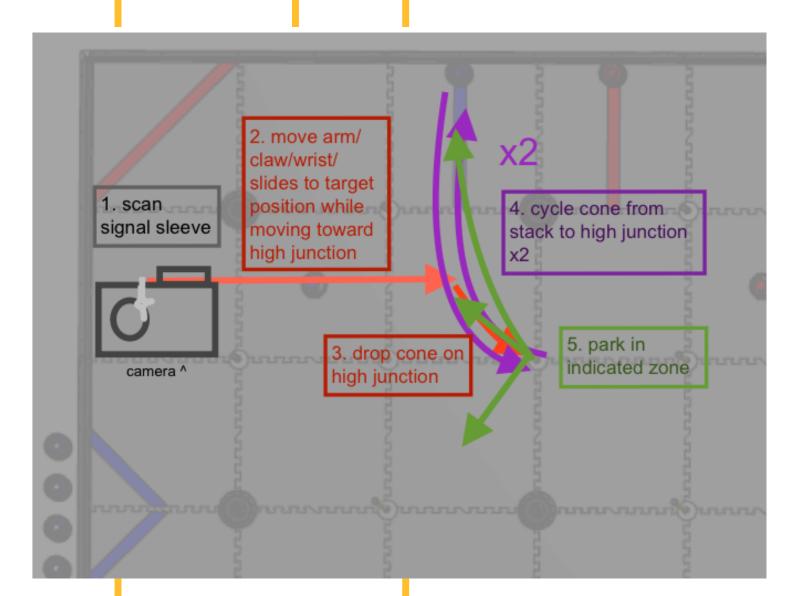
FIRST - BUILT WITH GOBILDA PARTS AND RUBBER BANDS
NOTABLE: FLIMSY PARTS, DID NOT ALIGN PROPERLY FOR A SECURE
GRIP

SECOND - 3D PRINTED DESIGN FROM LOONY SQUAD NOTABLE: MOLDED GRIP AROUND CONE ALONG WITH A STRONGER SERVO MAKES IT MORE SECURE

PROGRAMMING

AUTONOMOUS PERIOD

- 1. DETECT CONE ROTATION
 A. USING APRIL TAGS
- 2. PLACE PRELOAD ON HIGH JUNCTION
- 3. CYCLE 2 CONES FROM CONE STACK ONTO THE HIGH JUNCTION
- 4. PARK IN THE INDICATED ZONE



APRIL TAGS

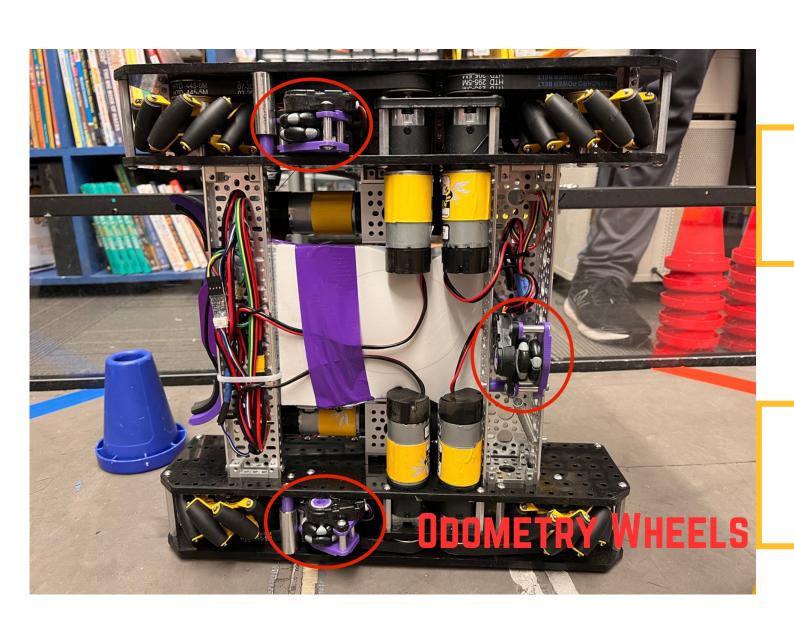
- RELIABLE WAY TO DETECT CONE POSITION
- WORKS IN ALL APPLICABLE LIGHTING CONDITIONS





Tag25h9

Tag36h11



LOCALIZATION

WE LOCALIZE USING THREE WHEEL ODOMETRY AND THE ROADRUNNER LOCALIZER

DRIVER ENHANCEMENTS

- MACRO BUTTONS FOR DROPPING AND FLIPPING THE CLAW OR PICKING UP AND RAISING THE SLIDES
- REVERSED DRIVING DIRECTIONS WHEN ARM FLIPPED FOR MORE LOGICAL DRIVING
- MACROS FOR THE DIFFERENT CONE STACK AND JUNCTION HEIGHTS FOR MORE ACCURATE CONE PLACEMENT

PROGRAMMING

NON-BLOCKING AUTONOMOUS CONTROL LOOP

OUR AUTONOMOUS RELIES ON AN ASYNCHRONOUS CONTROL LOOP WHERE WE CAN TRIGGER ARM, WRIST, AND CLAW EVENTS AT DIFFERENT BOT POSITIONS. THIS ALLOWS US TO EFFICIENTLY MOVE THE ROBOT IN TANDEM WITH THESE ARM, WRIST, AND CLAW MOVEMENTS IN A PRECISE FASHION.

ARMITRAGE PID CONTROL

OUR WRIST CLAW PRESENTED US WITH A NEW AND COMPLEX WAY TO MANIPULATE CONES, AND WITH THAT CAME NEW AND COMPLEX SOFTWARE CHALLENGES.

SOME CHALLENGES INCLUDED...

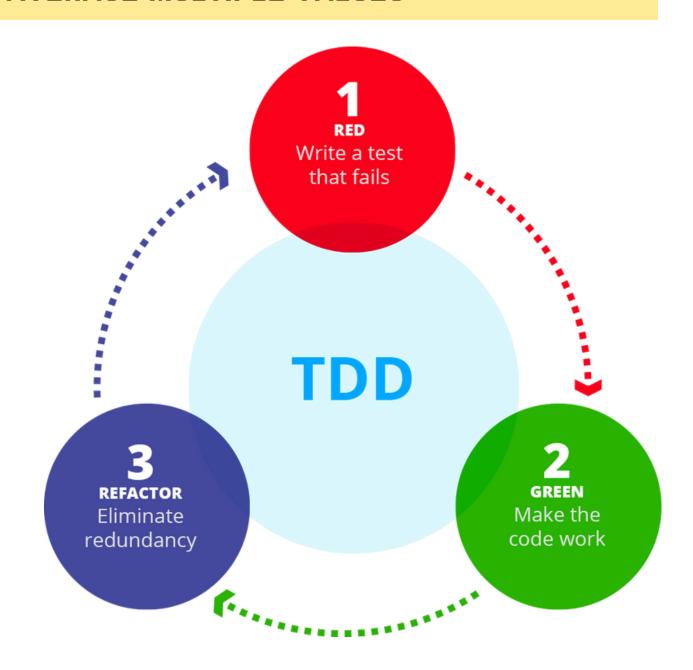
- 1. BOTH LINEAR SLIDE MOTORS HAVE TO OPERATE IN SYNC
- 2. BOTH SERVOS ON THE ARM HAVE TO OPERATE IN SYNC
- 3. THE SLIDES CANNOT STOP TO ABRUPTLY OR ELSE THE BELTS WILL SLIP
- 4. DISTANCE SENSOR REPORTED INCONSISTENT VALUES

HOW WE OVERCAME THEM...

- 1. DESIGNED A PROPORTIONAL CONTROL SYSTEM USING THEIR ENCODERS TO MAINTAIN SYNCHRONICITY
- 2. DESIGNED A SYSTEM WHERE THE SERVOS CAN ONLY BE ACCESSED AS A PAIR
- 3. MADE A MAXIMUM ACCELERATION USING PID AND THE SIGMOID FUNCTION
- 4. IMPLEMENTED CUSTOM ALGORITHM TO AVERAGE MULTIPLE VALUES

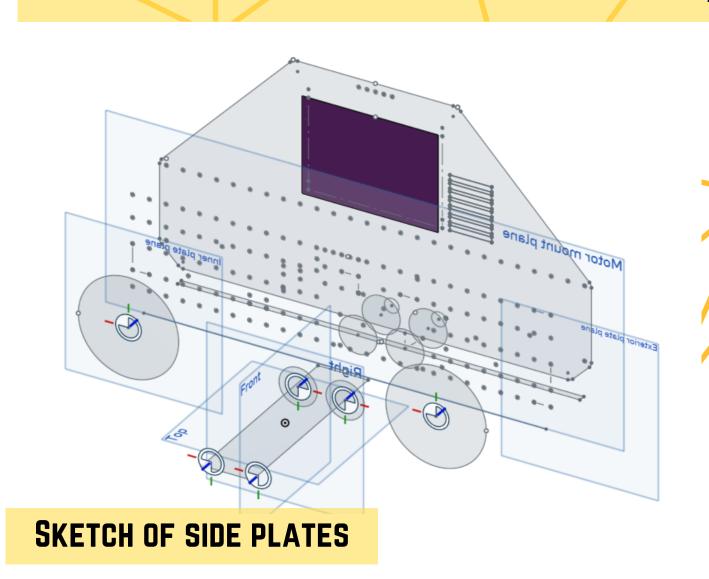
TEST DRIVEN DEVELOPMENT

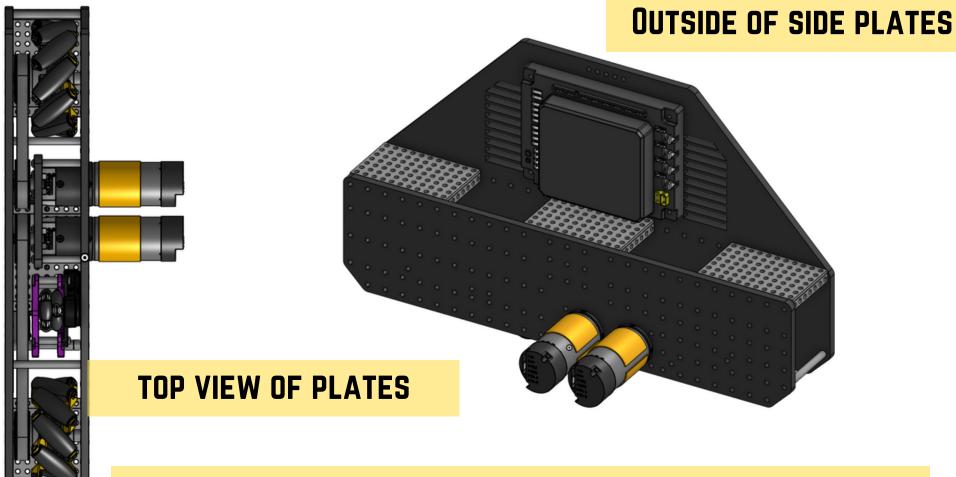
WE DECIDED TO USE TEST DRIVEN
DEVELOPMENT TO RAPIDLY TEST OUR PID
SYSTEM. EVEN WITH OUR LITTLE
KNOWLEDGE OF THE PROCESS AT THE
BEGINNING OF THE SEASON, WE WERE ABLE
TO LEARN THE PARADIGM, AND GREATLY
SPEED UP THE DEVELOPMENT PROCESS.



DIGITAL FABRICATION

WE USE ONSHAPE TO DOCUMENT OUR DESIGN PROCESS AND CREATE CUSTOM PARTS, AS WELL AS VIRTUALLY CONSTRUCT OUR ROBOT. THIS HELPS US TO VISUALIZE AND EFFICIENTLY EDIT OUR ITERATIONS, WHICH HELPED A LOT IN THE DESIGNING/CREATION OF OUR SIDE PLATES.





CHASSIS PLATES

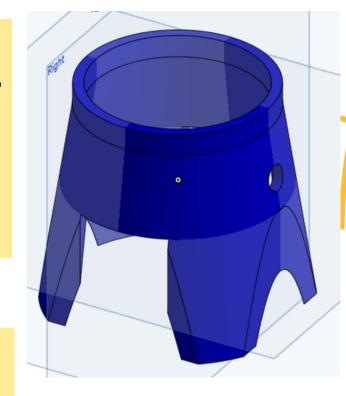
BEFORE LASER-CUTTING OUR CUSTOM SIDE PLATES, WE HAD TO DESIGN THEM IN CAD. DURING THIS PROCESS, WE LEARNED MANY NEW THINGS, INCLUDING HOW TO INTEGRATE CUSTOM PARTS AND COTS PARTS IN CAD.

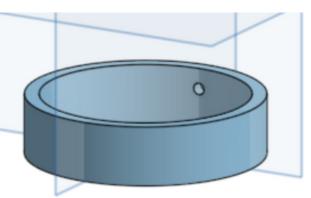
BECAUSE CREATING CUSTOM CHASSIS
PLATES REQUIRED EXTENSIVE KNOWLEDGE
OF CAD, MANY OF THE SKILLS DISPLAYED
HERE WERE LEARNED BY OUR MEMBERS IN
LESS THAN 3 WEEKS.

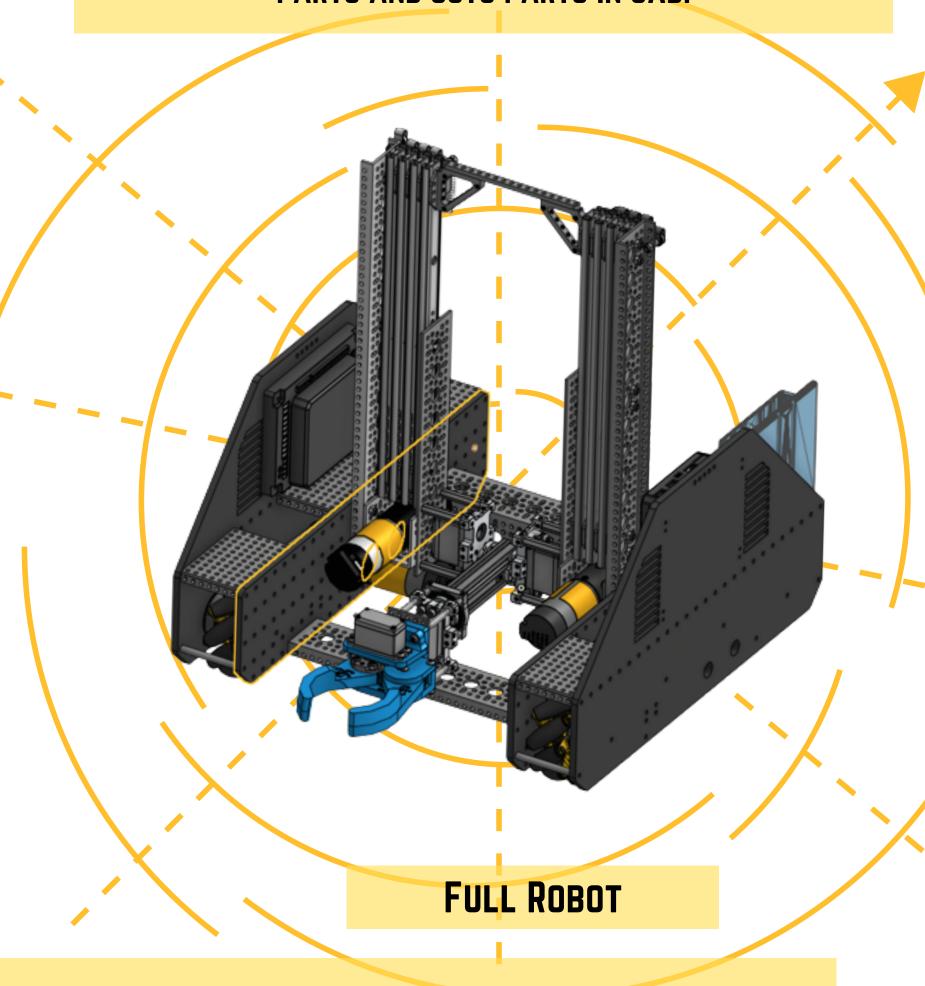
BEACON

OUR FIRST BEACON
WAS DESIGNED TO SIT
ON THE TOP OF THE
CONE, ABOVE THE
CLAW.

OUR SECOND BEACON
SITS BETWEEN THE
BOTTOM OF THE CONE
AND THE CLAW SO THAT
WHEN OUR ARM ROTATES,
THE BEACON DOESN'T
FALL OFF THE CONE.







ALONG WITH THE MANY CUSTOM PARTS ON OUR ROBOT, WE ALSO HAVE OPEN-SOURCE PARTS MADE BY OTHER TEAMS. THESE PARTS BEING, THE ODOMETRY WHEEL HOUSINGS--MADE BY PRIMITIVE DATA TEAM 18209, AND OUR CURRENT CLAW--DESIGNED BY LOONY SQUAD, A TEAM OF 5 THAT ONLY WORKS ON CAD.

OUTREACH







OPEN HOUSE - 10/22/22

DURING OUR SCHOOL'S OPEN HOUSE,
SOME OF OUR TEAM MEMBERS TOOK
TIME OUT OF THEIR WEEKENDS TO COME
PROMOTE FIRST AND THE ELECTRIC
QUAHOGS. WE TALKED TO OVER THIRTY
POTENTIAL WHEELER STUDENTS AND
THEIR FAMILIES: SPREADING THE WORD
ABOUT FIRST, OUR ROBOT, AND AWARDS.
HOPEFULLY CONVINCING THEM TO JOIN
THEIR SCHOOL'S ROBOTICS TEAM,
WHEREVER THEY ENDED UP ENROLLING!

WE HAVE OBTAINED OVER 246 NEW FOLLOWERS SINCE SEPTEMBER OF 2022, ADDING TO OUR TOTAL OF 506 FOLLOWERS! WE POST WEEKLY CONTENT, AND USE THE SOCIAL MEDIA PLATFORM TO KEEP IN TOUCH WITH OTHER FTC TEAMS. ON OUR INSTAGRAM PAGE, WE AIM TO SHARE THE **MUTI-LAYERED PARTICIPATION REQUIRED** BY FIRST BY POSTING BOTH OUR OUTREACH WORK AND LANDMARK COMPETITION MOMENTS. ONE OF OUR VIDEOS HAS OVER 1,700 VIEWS, WHICH WE ARE VERY PROUD OF! OUR LEAD PROGRAMMER CREATED OUR ELECTRIC QUAHOGS WEBSITE, WHERE WE TRY TO POST BLOGS IN ORDER TO KEEP PEOPLE UPDATED ON OUR WORK.

ASSISTING BLACKSTONE ACADEMY
BULLDOGS- 10/25/22

WE HOSTED THE BLACKSTONE ACADEMY
BULLDOGS AND SHOWED THEM THE
ROPES OF BEING A PART OF THE FTC
COMMUNITY! WE ASSISTED THEM IN
CREATING THEIR INSTAGRAM ACCOUNT-WHICH HAS OVER 70 FOLLOWERS--,
PROVIDED TIPS ON TEAM ORGANIZATION
AND GAVE THEM AN INTRODUCTION TO
CODING WITH ONBOT JAVA. THEY WERE
A VERY NICE AND CHEERFUL TEAM, AND
WE CANNOT WAIT TO SEE THEM AGAIN!

HOTING QUALIFIER - 1/7/23

WE HAD THE AMAZING OPPORTUNITY OF HOSTING THE FIRST RI 2023 QUALIFIER AT OUR SCHOOL! WE HOSTED AROUND 12 FTC TEAMS, GIVING US THE CHANCE TO MEET AND TALK WITH THEM ABOUT STRATEGIES. WE WERE ALSO ABLE TO RECONNECT WITH OTHER TEAMS THAT WE HAVE MET IN THE PAST. IT WAS A WONDERFUL WAY TO SHOW OUR NEW MEMBERS WHAT QUALIFIERS ENTAILED. WE HAD AN AMAZING TIME HOSTING AND WOULD LOVE TO DO IT AGAIN NEXT YEAR!



OUTREACH

LEARNING COMMUNITY - 12/4/22

MEMBERS OF TEAM 252, ASSISTED BY MEMBERS FROM TEAM 636 OCCAM'S RAZOR CLAMS, WENT TO THE LEARNING COMMUNITY CHARTER SCHOOL, WHERE 97% OF THEIR STUDENTS IDENTIFY AS PEOPLE OF COLOR, TO RUN A WORKSHOP WITH A CLASS OF THIRD-GRADERS! OUR TEAMMATES TALKED TO FOURTEEN STUDENTS ABOUT ROBOTICS AND STEM, AND LED A WORKSHOP. THE WORKSHOP HAD STUDENTS HAD MAKE BRIDGES WITH POPSICLE STICKS. THIS ACTIVITY WAS A LESSON IN HOW IMPORTANT THE DESIGN PROCESS IS, AS THEY HAD TO CREATE A DESIGN BEFORE BUILDING. IT WAS A LOT OF FUN AND WE ARE ALREADY PLANNING TO GO BACK AND DO ANOTHER WORKSHOP!







WE HOSTED A LECTURE BY PROFESSOR
BRENNAN PHILLIPS, AN UNDERWATER
ROBOTICS PROFESSOR AT THE UNIVERSITY
OF RHODE ISLAND. THROUGH HIS TALK, THE
AUDIENCE WAS ABLE TO LEARN ABOUT:
PROFESSOR BRENNAN'S LINE OF WORK,
HOW IMPORTANT ENGINEERING AND
ROBOTICS ARE TO OCEAN EXPLORATION,
AND ALL OF THE OPPORTUNITIES URI
PROVIDES TO HIGHSCHOOLERS AND
COLLEGE STUDENTS ALIKE. AROUND THIRTY
MEMBERS OF OUR COMMUNITY CAME
(INCLUDING OUR TEAM'S MEMBERS). IT
WAS A VERY EDUCATIONAL AND
INTERESTING LECTURE!

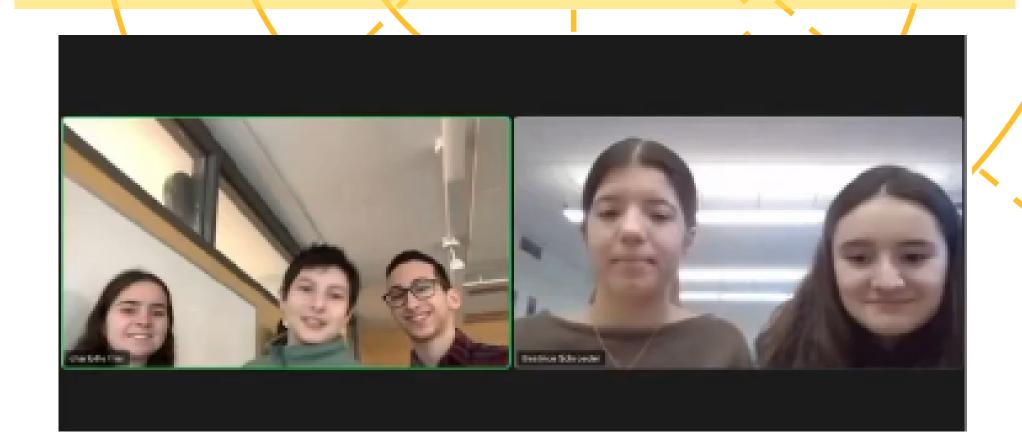


Providence Public Library

THE PROVIDENCE PUBLIC LIBRARY - 3/8
ON MARCH 8TH, WE WILL HOST A WORKSHOP AT THE PROVIDENCE
PUBLIC LIBRARY! WE WILL BE VISITING THE STEAM CLUB FOR
KIDS AGES 6-10 AND WE WILL BE TALKING TO THEM A LITTLE BIT
ABOUT FIRST AND HELPING THEM CREATE FUN CRAFTS.

CALLING TEAM 20789, RIVERDALE NY - 1/10/23

WE HAD THE OPPORTUNITY TO MEET TEAM 20789 FROM RIVERDALE, NY! WE SPOKE TO EACH OTHER ABOUT STRATEGY AND OUTREACH APPROACH. IT WAS INTERESTING AND EXCITING TALKING WITH THEM. WE BOTH LEARNED A LOT FROM EACH OTHER!







VARTAN GREGORIAN STEM WORKSHOP- 2/15/23

Vartan

Gregori<mark>a</mark>n

Elementary School

FOUR OF OUR MEMBERS WENT TO THE VARTAN GREGORIAN PUBLIC ELEMENTARY SCHOOL WHERE WE HELD A FUN STEM WORKSHOP FOR 2ND AND 3RD GRADERS! DURING THE WORKSHOP, APART FROM BUILDING DANCING ROBOTS, WE TAUGHT THE SEVENTEEN STUDENTS THE IMPORTANCE OF BEING PATIENT AND TO BE OK WITH MAKING MISTAKES. WE ARE PLANNING ON HOSTING ANOTHER WORKSHOP AT THIS SCHOOL!



OUTREACH

ROCHAMBEAU LIBRARY WORKSHOPS

WE ASSISTED OUR SISTER TEAM, TEAM 636 OCCAM'S RAZOR CLAMS, WITH ACTIVITIES THEY ARRANGED AT THE ROCHAMBEAU LIBRARY, A PUBLIC LIBRARY IN OUR COMMUNITY. ON DECEMBER 12, WE READ STEM THEMED PICTURE BOOKS ALOUD TO YOUNG CHILDREN. WE RETURNED ON JANUARY 11, WHERE WE HELD A WORKSHOP TEACHING CHILDREN FROM 4-11 YEARS OLD HOW TO BUILD THEIR VERY FIRST ROBOT! THE ROBOTS IN QUESTION WERE SIMPLE WIGGLE BOTS MADE WITH A TOOTHBRUSH HEAD, MINI VIBRATING MOTOR, BATTERY, AND TAPE. AT THESE EVENTS WE WERE ABLE TO TALK ABOUT OUR TIME WITHIN FIRST AND ENCOURAGE THE YOUNG STUDENTS TO LOOK FURTHER INTO STEM!

PROVIDENCE BIKE COLLECTIVE12/4/22

WE REACHED OUT TO THE
PROVIDENCE BIKE COLLECTIVE
SEEKING TO FORM A RELATIONSHIP,
HELP AT THE SHOP, AND LEARN
FROM EACH OTHER. WE HELPED
MOVE THEM MOVE TO THEIR NEW
LOCATION AND PAINT IT, WE ARE
CURRENTLY IN THE PROCESS OF
PLANNING TO HELP THEM DESIGN
THEIR NEW SPACE, AND
HOST/ATTEND WORKSHOPS.



Wheeler Robotics Behind the Bots Flectric Juahogs Monday, February 27th 3:30pm - 4:30pm Rochambeau Library - 708 Hope Street

BEHIND THE BOTS - 2/27/23

Providence, RI 02906

WE COLLABORATED WITH 636 OCAM'S RAZOR CLAMS TO CREATE AN EVENT FOR THE ROCHAMBEAU PUBLIC LIBARY. THIS SPECIFICALLY WAS TARGETED TO KIDS AGES 12+ AND FOCUSED ON THE MECHANICS OF FIRST AND HOW BOTH OUR TEAMS FUNCTION. WE ALSO DID A STEM THEMED CRAFT AND EXPLAINED TO BOTH KIDS AND THEIR FAMILIES HOW FTC HAS CHANGED OUR LIVES FOR THE BETTER.